APPROXIMATION RESULTS FOR α-ROSEN FRACTIONS

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ABSTRACT. In this article we generalize Borel's classical approximation results for the regular continued fraction expansion to the α-Rosen fraction expansion, using a geometric method. We use α-Rosen fractions to give a Haas-Series-type result about all possible good approximations for the α for which the Legendre constant is larger than the Hurwitz constant.

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1. Introduction

In 1798 Legendre proved the following result [15].

THEOREM 1. *Let* $x \in \mathbb{R} \setminus \mathbb{Q}$ *and* $\frac{p_n}{q_n}$ *be the nth regular continued fraction convergent of* x, $n \geq 0$. *If* $p, q \in \mathbb{Z}$, $q > 0$, *and* $\gcd(p,q) = 1$, *then*

$$\left| x - \frac{p}{q} \right| < \frac{1}{2q^2} \quad \text{implies that} \quad \begin{bmatrix} p \\ q \end{bmatrix} = \begin{bmatrix} p_n \\ q_n \end{bmatrix} \quad \text{for some } n \geq 0.$$

Legendre's Theorem is one of the main reasons for studying continued fractions, because it tells us that good approximations of irrational numbers by rational numbers are given by continued fraction convergents. We call the best possible coefficient of $\frac{1}{q^2}$, independent of x, the Legendre constant. It is $\frac{1}{2}$ for regular continued fraction (RCF) expansions. For the nearest integer continued fraction expansion (NICF) the Legendre constant is g^2, where $g = \frac{\sqrt{5}-1}{2} \approx 0.61$ is the golden number; see [11].

DEFINITION 2. Let $x \in [0,1) \setminus \mathbb{Q}$ and $\frac{p_n}{q_n}$ be the nth regular continued fraction convergent of x, $n \geq 0$. The approximation coefficient $\Theta_n = \Theta_n(x)$ is defined by

$$\Theta_n = q_n^2 \left| x - \frac{p_n}{q_n} \right| \quad \text{for} \quad n \geq 0.$$

We usually suppress the dependence of Θ_n on x in our notation. The approximation coefficient gives a numerical indication of the quality of the approximation; for the RCF it easily follows that $\Theta_n \leq 1$. For the RCF-expansion we have the following classical theorems by Borel (1905) [1] and Hurwitz (1891) [10] about the quality of the approximations.

THEOREM 3. *For every irrational number x, and every $n \geq 1$*

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} < \frac{1}{\sqrt{5}}.$$

The constant $1/\sqrt{5}$ is best possible.

REMARK 4. If we replace $\frac{1}{\sqrt{5}}$ by a smaller constant C, then there are countably infinitely many irrational numbers x for which

$$\left| x - \frac{p}{q} \right| \leq \frac{C}{q^2}$$

holds for only finitely many pairs of integers p and q. An example of such a number is the small golden number g.

Because $\frac{1}{\sqrt{5}} < \frac{1}{2}$ the results of Legendre and Borel imply Hurwitz's Theorem that states that for every irrational number x there exist infinitely many pairs of integers p and q, such that

$$\left| x - \frac{p}{q} \right| < \frac{1}{\sqrt{5}} \frac{1}{q^2}.$$

We call the best possible coefficient of $\frac{1}{q^2}$ in this inequality the Hurwitz constant. It is $\frac{1}{\sqrt{5}}$ for RCF-expansions.

J.C. Tong [19, 20] generalized Borel's result for the nearest integer continued fraction expansion (NICF). He showed that for the NICF there exists a 'spectrum,' i.e., there exists a sequence of constants $(c_k)_{k \geq 1}$, monotonically decreasing to $1/\sqrt{5}$, such that for all irrational numbers x the minimum of any block of $k+2$ consecutive NICF-approximation coefficients is smaller than c_k.

THEOREM 5. (Tong) *For every irrational number x and all positive integers n and k one has*

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k}\} < \frac{1}{\sqrt{5}} + \frac{1}{\sqrt{5}} \left(\frac{3 - \sqrt{5}}{2} \right)^{2k+3}.$$

The constant $c_k = \frac{1}{\sqrt{5}} + \frac{1}{\sqrt{5}} \left(\frac{3-\sqrt{5}}{2}\right)^{2k+3}$ is best possible.

In [9] Hartono and Kraaikamp showed how Tong's result follows by a geometrical method based on the natural extension of the NICF. The method will be discussed in Section 2. In [13] this method was extended to Rosen fractions. A real number r/s is called a G_q-rational if it has a finite (α)-Rosen expansion, and is a G_q-irrational otherwise. We have the following result.

THEOREM 6. *Fix $q = 2p$, with $p \in \mathbb{N}, p \geq 2$ and let $\lambda = \lambda_q = 2\cos\frac{\pi}{q}$. For every G_q-irrational number x and all positive n and k, one has*

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(p-1)}\} < c_k,$$

with

$$c_k = \frac{-\tau_{k-1}}{1 + (\lambda - 1)\tau_{k-1}} \quad and \quad \tau_k = \left[\left(-1:2, (-1:1)^{p-2}\right)^k, (-2,3)\right].$$

The constant c_k is best possible.

A similar theorem was derived for the case that q is odd. In this article we derive Borel results for both even and odd α-Rosen fractions; c.f. Theorem 10.

1.1. α-Rosen fractions

Let $q \geq 3, \lambda = \lambda_q = 2\cos\frac{\pi}{q}$ and let $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$. The α-Rosen fraction operator $T_\alpha : [(\alpha - 1)\lambda, \alpha\lambda) \to [(\alpha - 1)\lambda, \alpha\lambda)$ is defined by

$$T_\alpha(x) = \frac{\varepsilon}{x} - \lambda \left\lfloor \frac{\varepsilon}{\lambda x} + 1 - \alpha \right\rfloor \quad \text{if} \quad x \neq 0 \quad \text{and} \quad T_\alpha(0) := 0. \tag{7}$$

Repeatedly applying this operator to $x \in [(\alpha - 1)\lambda, \alpha\lambda)$ yields the α-Rosen expansion of x. Put

$$d(x) = \left\lfloor \left| \frac{1}{\lambda x} \right| + 1 - \alpha \right\rfloor \quad \text{and} \quad \varepsilon(x) = \text{sgn(x)}. \tag{8}$$

Furthermore, for $n \geq 1$ with $T_\alpha^{n-1}(x) \neq 0$ put

$$\varepsilon_n(x) = \varepsilon_n = \epsilon\left(T_\alpha^{n-1}(x)\right) \quad \text{and} \quad d_n(x) = d_n = d\left(T_\alpha^{n-1}(x)\right).$$

This yields a continued fraction of the type

$$x = \cfrac{\varepsilon_1}{d_1\lambda + \cfrac{\varepsilon_2}{d_2\lambda + \ldots}} = [\varepsilon_1 : d_1, \varepsilon_2 : d_2, \ldots],$$

where $\varepsilon \in \{\pm 1\}$ and $d_i \in \mathbb{N}^+$.

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In this article we derive a Borel-type result for α-Rosen fractions. Let q be fixed. Haas and Series [8] showed that for every G_q-irrational x there exist infinitely many G_q-rationals r/s, such that $s^2 \left| x - \frac{r}{s} \right| \leq \mathcal{H}_q$, where the Hurwitz constant $\mathcal{H}_q$ is given by

$$\mathcal{H}_q = \begin{cases} \dfrac{1}{2} & \text{if } q \text{ is even,} \\ \dfrac{1}{\sqrt{\lambda^2 - 4\lambda + 8}} & \text{if } q \text{ is odd.} \end{cases} \tag{9}$$

In this paper the following Borel result is obtained.

THEOREM 10. *Let $\alpha \in [1/2, 1/\lambda]$ and denote the nth α-Rosen convergent by p_n/q_n. For every G_q-irrational x there are infinitely many $n \in \mathbb{N}$ for which*

$$q_n^2 \left| x - \frac{p_n}{q_n} \right| \leq \mathcal{H}_q.$$

The constant $\mathcal{H}_q$ is best possible.

We remarked that for regular continued fractions the results of Borel and Legendre imply Hurwitz's result. For Rosen fractions, the case $\alpha = \frac{1}{2}$ it follows from Nakada [17] that the Legendre constant is smaller than the Hurwitz constant $\mathcal{H}_q$ (both in the odd and even case). This means that there might exist G_q-rationals r/s for which

$$\Theta(x, r/s) = s^2 \left| x - \frac{r}{s} \right| \leq \mathcal{H}_q,$$

i.e., with "quality" $\Theta(x, r/s)$ smaller than $\mathcal{H}_q$, that are not found as Rosen-convergents. So a direct continued fraction proof of the generalization by Haas and Series [8] of Hurwitz's results can not be given for standard Rosen fractions.

1.2. Legendre and Lenstra constants

In the early 1980s H.W. Lenstra conjectured that for regular continued fractions for almost all x and all $z \in [0, 1]$, the limit

$$\lim_{n \to \infty} \frac{1}{n} \#\{1 \leq j \leq n \,|\, \Theta_j(x) \leq z\}$$

exists and equals the distribution function F defined by

$$F(z) = \begin{cases} \dfrac{z}{\log 2} & \text{if } 0 \leq z \leq \frac{1}{2}, \\ \dfrac{1 - z + \log 2z}{\log 2} & \text{if } \frac{1}{2} \leq z \leq 1. \end{cases}$$

A version of this conjecture had been formulated by W. Doeblin [6] before. In 1983 W. Bosma *et al.* [2] proved the Doeblin-Lenstra-conjecture for regular continued fractions and Nakada's α-expansions for $\alpha \in \left[\frac{1}{2}, 1\right]$.

A prominent feature of F is that there exists a unique largest positive constant $\mathcal{L}$ such that $F(z)$ is linear for $z \in [0, \mathcal{L}]$. For the RCF we have $\mathcal{L} = \frac{1}{2}$. In [17], Nakada calls $\mathcal{L}$ the Lenstra constant and shows that for a large class of continued fractions this Lenstra constant is equal to the Legendre constant. Using Lenstra constants, it was shown in [12] that the so-called mediant Rosen map has a Legendre constant larger than the Hurwitz constant $\mathcal{H}_q$, thus yielding a Hurwitz result. These results were obtained using the Lenstra constant. We derive a Hurwitz result for each odd q, using certain α-Rosen fractions.

The outline of this article is as follows. In Section 2 we give some general definitions for the natural extensions for α-Rosen fractions and explain briefly how our method works. The even and odd case have different properties and we handle the details in two separate sections. The Borel result for the various subcases of even α-Rosen fractions are derived in Section 3, and the odd case is given in Section 4. In Section 5 we find the Lenstra constants $\mathcal{L}_\alpha$ for α-Rosen fractions and thereby conclude for which values of α we can derive a Hurwitz result.

2. The natural extension for α-Rosen fractions

In this section we introduce the necessary notation. Recall from (7) that

$$T_\alpha(t) = \frac{\varepsilon(t)}{t} - d(t)\lambda \quad \text{with} \quad \varepsilon(t) = \mathrm{sgn}(t) \quad \text{and} \quad d(t) = \left\lfloor \frac{\varepsilon}{\lambda t} + 1 - \alpha \right\rfloor.$$

DEFINITION 11. For fixed q and α the natural extension map $\mathcal{T}_\alpha : \Omega_\alpha \to \Omega_\alpha$ is given by

$$\mathcal{T}_\alpha(t, v) = \left(T_\alpha(t), \frac{1}{d(t)\lambda + \varepsilon(t)v} \right).$$

The shape of the domain Ω_α on which the two-dimensional map $\mathcal{T}_\alpha$ is bijective a.e. was constructed in [5]. We derive our results using a geometric method based on the natural extensions Ω_α. The shape of Ω_α depends on α and we give the explicit formulas for each of the different cases in the appropriate sections; see, e.g., the beginning of Subsection 3.1 for Ω_α when q is even and $\alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$. The natural extension also depends on q, but for ease of notation we suppress this dependence and write Ω_α instead of $\Omega_{\alpha,q}$.

We use constants l_n and r_n to describe Ω_α, where

$$l_0 = (\alpha - 1)\lambda \quad \text{and} \quad l_n = T_\alpha^n(l_0) \qquad \text{for} \ \ n \geq 0,$$
$$r_0 = \alpha\lambda \qquad \text{and} \quad r_n = T_\alpha^n(r_0) \qquad \text{for} \ \ n \geq 0.$$

The orbit of $-\frac{\lambda}{2}$ in the case $\alpha = \frac{1}{2}$ plays an important role in describing the natural extensions. We define $\varphi_j = T_{\frac{1}{2}}^j(-\frac{\lambda}{2})$.

We set $\delta_d = \frac{1}{(\alpha + d)\lambda}$ for all $d \geq 1$. So if $\delta_d < x \leq \delta_{d-1}$, we have $d(x) = d$ and $\varepsilon(x) = +1$. For x with $-\delta_{d-1} \leq x < -\delta_d$ we have $d(x) = d$ and $\varepsilon(x) = -1$; also see (8).

We often use the auxiliary sequence B_n given by

$$B_0 = 0, \quad B_1 = 1, \quad B_n = \lambda B_{n-1} - B_{n-2}, \quad \text{for} \ \ n = 2, 3, \ldots \qquad (12)$$

Note that $B_n = \sin \frac{n\pi}{q} / \sin \frac{\pi}{q}$. If $q = 2p$ for $p \geq 2$, we find from $\sin \frac{(p-1)\pi}{2p} = \sin \frac{(p+1)\pi}{2p}$ that

$$B_{p-1} = B_{p+1} = \frac{\lambda}{2} B_p \quad \text{and} \quad B_{p-2} = \left(\frac{\lambda^2}{2} - 1\right) B_p. \qquad (13)$$

Similarly, in the odd case with $q = 2h + 3$ for $h \in \mathbb{N}$ we have that

$$B_{h+1} = B_{h+2}, \quad B_h = (\lambda - 1)B_{h+1} \quad \text{and} \quad B_{h-1} = \left(\lambda^2 - \lambda - 1\right) B_{h+1}. \qquad (14)$$

We define for $x \in [l_0, r_0)$ with α-Rosen expansion $[\varepsilon_1 : d_1, \varepsilon_2 : d_2, \ldots]$ the *future* t_n and the *past* v_n of x at time $n \geq 1$ by

$$t_n = [\varepsilon_{n+1} : d_{n+1}, \varepsilon_{n+2} : d_{n+2}, \ldots] \quad \text{and} \quad v_n = [1 : d_n, \varepsilon_n : d_{n-1}, \ldots, \varepsilon_2 : d_1].$$

We set $t_0 = x$ and $v_0 = 0$.

REMARK 15. Note that $\mathcal{T}_\alpha{}^n(x, 0) = (t_n, v_n)$ for $n \geq 0$.

The $(n-1)$st and nth approximation coefficients of x can be given in terms of t_n and v_n (see Section 5.1.2 of [4]) as

$$\Theta_{n-1} = \Theta_{n-1}(t_n, v_n) = \frac{v_n}{1 + t_n v_n} \quad \text{and} \quad \Theta_n = \Theta_n(t_n, v_n) = \frac{\varepsilon_{n+1} t_n}{1 + t_n v_n}. \qquad (16)$$

LEMMA 17. *The $(n+1)$st approximation coefficient of x can be expressed in terms of $d_{n+1}, \varepsilon_{n+1}$ and ε_{n+2} by*

$$\Theta_{n+1} = \Theta_{n+1}(t_n, v_n) = \frac{\varepsilon_{n+2}(1 - \varepsilon_{n+1} d_{n+1} t_n \lambda)(\lambda d_{n+1} + \varepsilon_{n+1} v_n)}{1 + t_n v_n}. \qquad (18)$$

P r o o f. First we use (16) to write

$$\Theta_{n+1} = \Theta_n(t_{n+1}, v_{n+1}) \frac{\varepsilon_{n+2} t_{n+1}}{1 + t_{n+1} v_{n+1}} = \varepsilon_{n+2} t_{n+1} \frac{\Theta_n}{v_{n+1}} = \frac{\varepsilon_{n+2} \varepsilon_{n+1} \frac{t_{n+1} t_n}{v_{n+1}}}{1 + t_n v_n}.$$

Then we use $t_{n+1} = \frac{\varepsilon_{n+1}}{t_n} - d_{n+1}\lambda$ and $v_{n+1} = \frac{1}{\lambda d_{n+1} + \varepsilon_{n+1} v_n}$ to find (18). $\qquad\square$

In view of (16) we define functions f and g on $[l_0, r_0)$ by

$$f(x) = \frac{\mathcal{H}_q}{1 - \mathcal{H}_q x} \quad \text{and} \quad g(x) = \frac{|x| - \mathcal{H}_q}{\mathcal{H}_q x}. \qquad (19)$$

Then for points $(t_n, v_n) \in \Omega_\alpha$ one has

$$\Theta_{n-1} \leq \mathcal{H}_q \Leftrightarrow v_n \leq f(t_n) \quad \text{and} \quad \Theta_n \leq \mathcal{H}_q \Leftrightarrow \begin{cases} v_n \leq g(t_n) & \text{if } t_n < 0 \\ v_n \geq g(t_n) & \text{if } t_n \geq 0. \end{cases} \qquad (20)$$

We define $\mathcal{D}$ as

$$\mathcal{D} = \left\{ (t, v) \in \Omega_\alpha \mid \min\left\{ \frac{v}{1 + tv}, \frac{|t|}{1 + tv} \right\} > \mathcal{H}_q \right\}, \qquad (21)$$

so $\min\{\Theta_{n-1}, \Theta_n\} > \mathcal{H}_q$ if and only if $(t_n, v_n) \in \mathcal{D}$.

See Figure 1 for an example of the position of $\mathcal{D}$ and of the graphs of f and g in Ω_α for $q = 4$.

3. Tong's spectrum for even α-Rosen fractions

Let $q = 2p$ for $p \in \mathbb{N}^+$, $p \geq 2$ and set $\lambda = 2\cos\frac{\pi}{q}$. As shown in [5] there are three subcases for the shape of Ω_α: we need to study $\alpha = \frac{1}{2}, \alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$ and $\alpha = \frac{1}{\lambda}$ separately. The following result, giving the ordering of the l_n and r_n, was essential in the construction of the natural extensions.

THEOREM 22. [5] *Let $q = 2p, p \in \mathbb{N}, p \geq 2$ and let l_n and r_n be defined as before. If $\frac{1}{2} < \alpha < \frac{1}{\lambda}$, then we have*

$$-1 < l_0 < r_1 < l_1 < \ldots < r_{p-2} < l_{p-2} < -\delta_1 < r_{p-1} < 0 < l_{p-1} < r_0 < 1,$$

$d_p(r_0) = d_p(l_0) + 1$ *and* $l_p = r_p$. *If $\alpha = \frac{1}{2}$, then we have*

$$-1 < l_0 < r_1 = l_1 < \ldots < r_{p-2} = l_{p-2} < -\delta_1 < r_{p-1} = 0 = l_{p-1} < r_0 < 1.$$

If $\alpha = \frac{1}{\lambda}$, then we have

$$-1 < l_0 = r_1 < l_1 = r_2 < \ldots < l_{p-2} = -\delta_1 = r_{p-1} < 0 < r_0 = 1.$$

Let $k \geq 1$ be an integer and put

$$
(\tau_k, \nu_k) =
\begin{cases}
\mathcal{T}_\alpha^{-k(p-1)}\left(\frac{-2}{3\lambda}, \lambda - 1\right) & \text{if } \alpha = \frac{1}{\lambda}, \\
\mathcal{T}_\alpha^{-k(p-1)}\left(-\delta_1, \lambda - 1\right), & \text{otherwise.}
\end{cases}
\tag{23}
$$

We prove the following result in this section.

THEOREM 24. *Fix an even $q = 2p$ with $p \geq 3$ and let $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$. There exists a positive integer K such that for every G_q-irrational number x and all positive n and $k > K$, one has*

$$
\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(p-1)}\} < c_k \quad \text{with } c_k = \frac{-\tau_{k-1}}{1 + \tau_{k-1}\nu_{k-1}}.
$$

For every integer $k \geq 1$ we have $c_{k+1} < c_k$. Furthermore, $\lim\limits_{k \to \infty} c_k = \dfrac{1}{2}$.

The case $\alpha = \frac{1}{2}$ was proven in [13]; c.f. Theorem 6. The proof for $\alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$ is given in Section 3.1. In Section 3.2 we use that the natural extension for the case $\alpha = \frac{1}{\lambda}$ is the mirror image of the one for $\alpha = \frac{1}{2}$ to prove Theorem 24 for $\alpha = \frac{1}{\lambda}$.

3.1. Even case with $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$

In this section we assume that $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$. In [5] the shape of Ω_α was determined.

DEFINITION 25. Set

$$
J_{2n-1} = [l_{n-1}, r_n) \quad \text{and} \quad J_{2n} = [r_n, l_n) \qquad \text{for} \quad n = 1, 2, \ldots, p-1,
$$
$$
J_{2p-1} = [l_{p-1}, r_0) \quad \text{and}
$$

$$
H_1 = \frac{1}{\lambda + 1}, \quad H_2 = \frac{1}{\lambda} \quad \text{and} \quad H_n = \frac{1}{\lambda - H_{n-2}} \quad \text{for} \quad n = 3, 4, \ldots, 2p-1.
$$

The domain of Ω_α upon which $\mathcal{T}_\alpha$ is bijective a.e. is given by

$$
\Omega_\alpha = \bigcup_{n=1}^{2p-1} J_n \times [0, H_n].
$$

We define

$$
\Omega_\alpha^+ = \{(t, v) \in \Omega_\alpha \mid t > 0\}.
$$

From the above description of the natural extension Ω_α it follows that the natural extension has $2p-1$ heights $H_1, \ldots, H_{2p-1}$. In [5] is is shown that $H_{i+1} > H_i$ for $i = 1, \ldots, 2p-2$,

$$
H_{2p-3} = \lambda - 1, \quad H_{2p-2} = \frac{\lambda}{2}, \quad H_{2p-1} = 1,
$$

and

$$l_{p-2} = \frac{\alpha\lambda^2 - 2}{(-\alpha\lambda^2 + 2\alpha + 1)\lambda}, l_{p-1} = \frac{(2\alpha - 1)\lambda}{2 - \alpha\lambda^2} \quad \text{and} \quad r_{p-1} = -\frac{(2\alpha - 1)\lambda}{2 - (1 - \alpha)\lambda^2}.$$

$$\text{(26)}$$

Note that Theorem 24 gives a result for $q \geq 6$. The case $q = 4$ behaves slightly differently, which we show in the following subsection.

3.1.1. The case $q = 4$

In this subsection we assume that $q = 2p = 4$, so $\lambda = \sqrt{2}$. In this case we have $H_1 = \sqrt{2} - 1, H_2 = \frac{1}{2}\sqrt{2}$ and $H_3 = 1$. We prove the following result.

THEOREM 27. *Let* $\lambda = 2\cos\frac{\pi}{4} = \sqrt{2}$, *let* $\alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$ *and let* τ_k *be as given in (23). There exists a positive integer K such that for every G_q-irrational number x and all positive n and $k \geq K$, one has*

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k}\} < c_k \quad \text{with} \quad c_k = \frac{\sqrt{2} - 1}{1 + \tau_{k-1}(\sqrt{2} - 1)}.$$

For every integer $k \geq 1$ we have $c_{k+1} < c_k$. Furthermore $\lim_{k\to\infty} c_k = \frac{1}{2}$.

We start by determining the shape of the region $\mathcal{D} \subset \Omega_\alpha$, see (21), where

$$\min\{\Theta_{n-1}, \Theta_n\} > \frac{1}{2}.$$

LEMMA 28. *Put* $\alpha_0 := \frac{4+\sqrt{2}}{8} = 0.676\ldots$ *For* $\alpha \in \left(\frac{1}{2}, \alpha_0\right)$ *the region $\mathcal{D}$ consists of one component $\mathcal{D}_1$, which is bounded by the lines $t = l_0$, $v = H_1$, and the graph of f; see Figure 1. If* $\alpha \in \left[\alpha_0, \frac{\sqrt{2}}{2}\right)$, *then $\mathcal{D}$ consists of two components: $\mathcal{D}_1$ and $\mathcal{D}_2$, where $\mathcal{D}_2$ is the region bounded by the lines $t = r_1$, $v = H_2$, and the graph of g; see Figure 2.*

P r o o f. Recall that $\mathcal{H}_q = \frac{1}{2}$. First assume that $t \geq 0$. The graphs of f and g do not intersect for $t \leq r_0$. Thus every point $(t_n, v_n) \in \Omega_\alpha^+$ is below the graph of f or above the graph of g. By (20) we have when $t \geq 0$ that $\min\{\Theta_{n-1}, \Theta_n\} < \frac{1}{2}$.

Assume that $t < 0$. The graphs of f and g intersect with the line $v = H_1$ in the point $(1 - \sqrt{2}, \sqrt{2} - 1)$, and we find that $l_0 < -\frac{1}{2} < -\delta_1 < 1 - \sqrt{2} < r_1$ for $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$. Since both f and g are monotonically increasing, we find that for $l_0 < t < r_1$ the intersection of $\mathcal{D}$ and Ω_α is $\mathcal{D}_1$.

One easily checks that $g(r_1) \leq H_2$ if and only if $\alpha \geq \alpha_0$. So we find that for $\alpha > \alpha_0$ and $r_1 < t < 0$ the intersection of $\mathcal{D}$ and Ω_α is $\mathcal{D}_2$ (for $\alpha = \alpha_0$ the region $\mathcal{D}_2$ consists of exactly one point, $(r_1, g(r_1))$); see Figure 2. $\qquad\square$
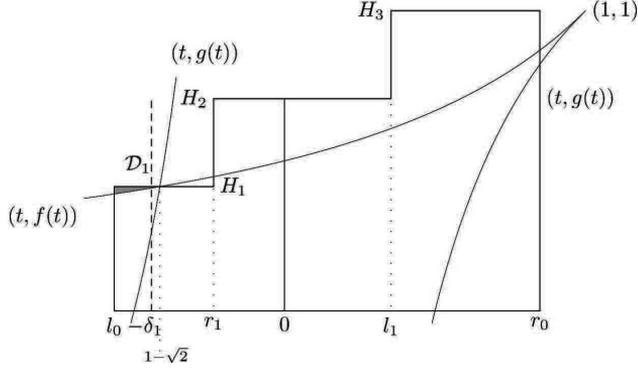
FIGURE 1. Here $q = 4$ and $\alpha = 0.6 < \alpha_0 = 0.676\ldots$ The region $\mathcal{D}$ consists of one component $\mathcal{D}_1$.
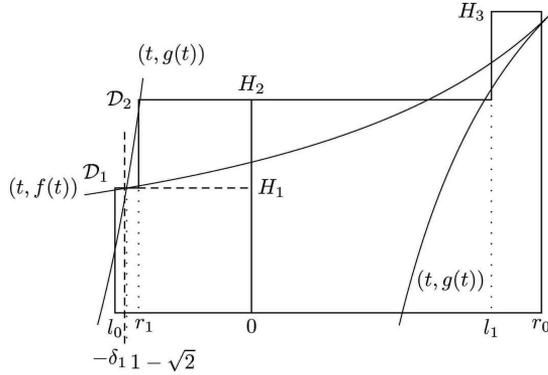

FIGURE 2. Here $q = 4$ and $\alpha = 0.68 > \alpha_0 = 0.676\ldots$ The region $\mathcal{D}$ consists of two components.

P r o o f   o f   T h e o r e m   27. Recall that $(\tau_k, \nu_k) = \mathcal{T}_\alpha^{-k}(-\delta_1, \lambda - 1)$. For $q = 4$ we find $\tau_1 = \frac{-1}{2\sqrt{2}-\delta_1}$, $\tau_k = [(-1 : 2)^k, -\delta_1]$ and $\nu_k = \sqrt{2} - 1$ for all k. Since T_α is strictly increasing on the interval $[-\delta_1, -\delta_2)$, we find $\tau_{k-1} < \tau_k$. In this case $\lim_{k\to\infty} \tau_k = [\overline{(-1 : 2)}] = \frac{-1}{\sqrt{2}+1} = 1 - \sqrt{2}$. We conclude that $\lim_{k\to\infty} \tau_k = 1 - \sqrt{2}$.

We find $c_{k+1} < c_k$, $\lim_{k\to\infty} c_k = \frac{\sqrt{2}-1}{1+(1-\sqrt{2})(\sqrt{2}-1)} = \frac{1}{2}$ and conclude that $c_k > \frac{1}{2}$ for all k.

We now focus on the orbit of points in $\mathcal{D}$ and start with $\mathcal{D}_1$. First, note that $\mathcal{T}_\alpha([l_0, -\delta_1) \times [0, H_1]) = [l_1, r_0) \times [H_2, 1] \subset \{(t, v) \in \Omega_\alpha | t \geq 0\}$. Therefore, if

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$(t_n, v_n) \in \mathcal{D}_1$ and $t_n \leq -\delta_1$, we have $\min\{\Theta_{n-1}, \Theta_n\} > \frac{1}{2}$, while $\Theta_{n+1} < \frac{1}{2}$. For these points we have proven Theorem 27 with $K = 1$.

Note that $(1 - \sqrt{2}, \sqrt{2} - 1)$ is a fixed-point of $\mathcal{T}_\alpha$. In particular, we have that $(1 - \sqrt{2}, \sqrt{2} - 1)$ is a repellent fixed-point for the first-coordinate map of $\mathcal{T}_\alpha$, and an attractive fixed point for the second coordinate map of $\mathcal{T}_\alpha$. Thus points $(t, v) \in \mathcal{D}_1$ with $t > -\delta_1$ move "left and up" under $\mathcal{T}_\alpha$. Noting that f is strictly increasing, we have that the region $\{(t, v) \in \mathcal{D}_1 | t \geq -\delta_1\}$ is mapped by $\mathcal{T}_\alpha$ inside $\mathcal{D}_1$.

Setting $\mathcal{D}_{1,k} := \{(t, v) \in \mathcal{D}_1 | \tau_{k-1} \leq t < \tau_k\}$, for $k \geq 1$, and $\mathcal{D}_{1,0} := \{(t, v) \in \mathcal{D}_1 | t < -\delta_1\}$, by definition of τ_k and $\mathcal{D}_{1,k}$, we have for $k \geq 1$ that

$$(t, v) \in \mathcal{D}_{1,k} \quad \text{implies} \quad \mathcal{T}_\alpha(t, v) \in \mathcal{D}_{1,k-1}.$$

We determine the maximum of Θ_{n-1}, Θ_n and Θ_{n+1} on $\mathcal{D}_{1,k}$ for $k \geq 1$.

LEMMA 29. Let $k \geq 1$ and $(t_n, v_n) \in \mathcal{D}_{1,k}$. Then

$$\Theta_{n-1} \leq \Theta_n \leq \Theta_{n+1}. \tag{30}$$

P r o o f. On $\mathcal{D}_{1,k}$ we have $d_{n+1} = 2$ and $\varepsilon_{n+1} = \varepsilon_{n+2} = -1$. From (16) we find

$$\Theta_{n-1} \leq \Theta_n \quad \text{if and only if} \quad v_n \leq -t_n,$$

and the latter inequality is true in view of the fixed point. From (18) we have

$$\Theta_{n+1} = \frac{-(1 + 2\sqrt{2}t_n)(2\sqrt{2} - v_n)}{1 + t_n v_n}$$

and we find

$$\Theta_n \leq \Theta_{n+1} \quad \text{if and only if} \quad v_n \leq \frac{7t_n + 2\sqrt{2}}{1 + 2\sqrt{2}t_n}.$$

On $\mathcal{D}_{1,k}$ the function $v(t) = \frac{7t + 2\sqrt{2}}{1 + 2\sqrt{2}t}$ is decreasing in t and $v(1 - \sqrt{2}) = \sqrt{2} - 1$. So $\Theta_n \leq \Theta_{n+1}$ on $\mathcal{D}_{1,k}$ for $k \geq 1$. $\qquad \square$

We conclude that for every point $(t_n, v_n) \in \mathcal{D}_{1,k}$ for $k \geq 1$

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} \leq \max_{(t,v) \in \mathcal{D}_{1,k}} \Theta_{n-1}(t, v).$$

We determine the maximum of Θ_{n-1} on $\mathcal{D}_{1,k}$. The partial derivatives of Θ_{n-1} are given by

$$\frac{\partial \Theta_{n-1}}{\partial t_n} = \frac{-v_n^2}{(1 + t_n v_n)^2} < 0 \quad \text{and} \quad \frac{\partial \Theta_{n-1}}{\partial v_n} = \frac{1}{(1 + t_n v_n)^2} > 0,$$

so on $\mathcal{D}_{1,1}$ we see that Θ_{n-1} attains its maximum in $(-\delta_1, \sqrt{2} - 1)$. Similarly on $\mathcal{D}_{1,k}$ we find that Θ_{n-1} attains its maximum in $(\tau_k, \sqrt{2} - 1)$, which is the top

left-hand vertex of $\mathcal{D}_{1,k}$. We find the values

$$c_1 = \frac{\sqrt{2}-1}{1-\delta_1(\sqrt{2}-1)} \quad \text{and} \quad c_k = \frac{\sqrt{2}-1}{1+\tau_{k-1}(\sqrt{2}-1)}.$$

One sees that if $(t_n, v_n) \in \mathcal{D}_{1,k}$ for some $k \geq 3$, then $(t_{n+1}, v_{n+1}) \in \mathcal{D}_{1,k-1}$, $(t_{n+2}, v_{n+2}) \in \mathcal{D}_{1,k-2}, \ldots, (t_{n+k-1}, v_{n+k-1}) \in \mathcal{D}_{1,1}$. It follows that

$$(t_n, v_n) \in \mathcal{D}_{1,k} \quad \text{implies} \quad \frac{1}{2} < \min\{\Theta_{n-1}, \ldots, \Theta_{n+k}\} < \Theta_{n-1}(\tau_{k-1}, \sqrt{2}-1) = c_k$$

$$\text{and } \Theta_{n+k+1} < \frac{1}{2}. \tag{31}$$

For $\alpha < \alpha_0$ the above implication (31) is actually an equivalence, since $\mathcal{D}_2$ is void for these values of α. Thus Theorem 27 for the case $q = 4$ and $\alpha < \alpha_0$ follows with $K = 1$.

We continue by studying the orbit of points in $\mathcal{D}_2$ and assume that $\alpha \in [\alpha_0, \frac{1}{\lambda})$, so $\mathcal{D}_2$ is non-empty.

It follows from the fact that $(1 - \sqrt{2}, \sqrt{2} - 1)$ is a repellent fixed-point on the first coordinate map of $\mathcal{T}_\alpha$, and an attractive fixed-point on the second coordinate map of $\mathcal{T}_\alpha$, that for $(t, v) \in \mathcal{D}_2$

$$1 - \sqrt{2} < r_1 < t < \pi_1(\mathcal{T}_\alpha(t,v)) \quad \text{and} \quad H_2 > v > \pi_2(\mathcal{T}_\alpha(t,v)) > \sqrt{2} - 1,$$

(here π_i is the projection on the ith coordinate), i.e., $\mathcal{T}_\alpha$ "moves" the point $(t, v) \in \mathcal{D}_2$ to the right, and "downwards towards" $\sqrt{2} - 1$.

Let $(t_1, \sqrt{2} - 1 + v_1)$ be a point in $\mathcal{D}_2$. The lowest point in $\overline{\mathcal{D}_2}$, the closure of $\mathcal{D}_2$, is given by $(r_1, g(r_1)) = (\frac{1-2\alpha}{\sqrt{2}\alpha}, \frac{(\sqrt{2}-4)\alpha+2}{2\alpha-1})$, so $0 < \frac{-(2+\sqrt{2})\alpha+1+\sqrt{2}}{2\alpha-1} < v_1$ for every point $(t_1, \sqrt{2} - 1 + v_1) \in \mathcal{D}_2$ and trivially $v_1 < 1$.

For the second coordinate we find

$$\pi_2(\mathcal{T}_\alpha(t_1, \sqrt{2}-1+v_1)) = \frac{1}{\sqrt{2}+1-v_1} = \sqrt{2} - 1 + \frac{\sqrt{2}-1}{\sqrt{2}+1-v_1}v_1.$$

For all points in $\mathcal{D}_2$ we have $d = 2$ and $\varepsilon = -1$. Thus in every consecutive step the second coordinate will be closer to the value $\sqrt{2} - 1$ by a factor $\frac{\sqrt{2}-1}{\sqrt{2}+1-v_1} < \frac{\sqrt{2}-1}{\sqrt{2}} < 1$. Hence there exists a smallest positive integer K such that for all $(t, v) \in \mathcal{D}_2$ one has $\mathcal{T}_\alpha^K(t, v) \notin \mathcal{D}_2$. In words: the region $\mathcal{D}_2$ is "flushed" out of $\mathcal{D}$ in K steps, and the implication in (31) is an equivalence for $k > K$. This proves Theorem 27. $\qquad\square$

REMARK 32. More can be said with (considerable) effort. We start by deriving α_1 such that for $\alpha \in [\alpha_0, \alpha_1]$ the region $\mathcal{D}_2$ is non-empty, but flushed after one iteration of $\mathcal{T}_\alpha$. We find α_1 by solving for which value of α we have that the point

$\mathcal{T}_\alpha(r_1, H_2) = (r_2, \frac{\sqrt{2}}{3})$ is on the graph of g. Using that $d(r_1) = 2$ for $\alpha \in \left[\alpha_0, \frac{1}{\lambda}\right)$ we find that the only solution is given by $\alpha_1 := \frac{24+\sqrt{2}}{36} = 0.70595\ldots$

So if $\alpha \in [\alpha_0, \alpha_1] = [\frac{4+\sqrt{2}}{8}, \frac{24+\sqrt{2}}{36}]$ and $(t_n, v_n) \in \mathcal{D}_2$, then $\min\{\Theta_{n-1}, \Theta_n\} > \frac{1}{2}$, and $\Theta_{n+1} < \frac{1}{2}$.

For $\alpha > \alpha_1$ and $i \geq 1$, we define the pre-images g_i of g for $t \in [1 - \sqrt{2}, \beta]$ by

$$v = g_i(t) \quad \Leftrightarrow \quad \pi_2\left(\mathcal{T}_\alpha^i(t,v)\right) = g\left(\pi_1\left(\mathcal{T}_\alpha^i(t,v)\right)\right),$$

i.e., the point (t, v) is on the graph of g_i if and only if $\mathcal{T}_\alpha^i(t, v)$ is on the graph of g. Note that for every $i \geq 1$ one has that $(1-\sqrt{2}, \sqrt{2}-1)$ is on the graph of g_i.

By definition of K_α it follows that the graph of g_i has a non-empty intersection with $\mathcal{D}_2$ if and only if $i = 1, \ldots, K_\alpha - 1$. These $K_\alpha - 1$ graphs g_i divide $\mathcal{D}_2$ like a "cookie-cutter" into regions $\mathcal{D}_{2,i}$ for $i = 1, \ldots, K_\alpha$; setting $g_0 := g$,

$$\mathcal{D}_{2,i} := \left\{(t,v) \in \mathcal{D}_2 \,|\, g_{i-1}(t) \leq v < \min\{H_2, g_i(t)\}\right\}.$$

We have that

$$(t_n, v_n) \in \mathcal{D}_{2,i} \quad \Rightarrow \quad \min\{\Theta_{n-1}, \ldots, \Theta_{n+i-1}\} > \frac{1}{2} \text{ and } \Theta_{n+i} < \frac{1}{2}.$$

In principle it is possible to determine the optimal constant $\tilde{c}_k$ for $(t_n, v_n) \in \mathcal{D}_2$ and $k = 1, \ldots, K - 1$ such that

$$\min\{\Theta_{n-1}, \ldots, \Theta_{n+k}\} < \tilde{c}_k.$$

In this way, Theorem 24 can be further sharpened.

REMARK 33. From the proof of Lemma 30 it easily follows that for points $(t_n, v_n) \in \mathcal{D}_2$

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} = \Theta_n.$$

The partial derivatives of Θ_n on $\mathcal{D}_2$ are given by

$$\frac{\partial \Theta_n}{\partial t_n} = \frac{-1}{(1 + t_n v_n)^2} < 0 \quad \text{and} \quad \frac{\partial \Theta_n}{\partial v_n} = \frac{t_n^2}{(1 + t_n v_n)^2} > 0.$$

EXAMPLE 34. An easy but tedious calculation yields that $\mathcal{T}_\alpha^2(r_1, H_2)$ is on the graph of g if $\alpha = \alpha_2 := \frac{140+\sqrt{2}}{200} = 0.707071\ldots$

For $\alpha \in (\alpha_1, \alpha_2]$ we have that $K_\alpha = 2$. For $\alpha \in (\alpha_1, \alpha_2]$ the region $\mathcal{D}_2$ consists of two parts: $\mathcal{D}_{2,1}$ and $\mathcal{D}_{2,2}$. The region $\mathcal{D}_{2,1}$ is immediately flushed and is therefore not interesting for us. For $(t_n, v_n) \in \mathcal{D}_{2,2}$ we have

$$\frac{1}{2} < \min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} < \Theta_n\left(\mathcal{T}_\alpha(r_1, H_2)\right) = 9\sqrt{2}\alpha - 6\sqrt{2}.$$

The comparable value of c_1 is

$$c_1 = \frac{\delta_1}{1 - \delta_1 H_1} = \frac{(\alpha + 1)(2 - \sqrt{2})}{\sqrt{2}\alpha + 2\sqrt{2} - 1}.$$

We find that $9\sqrt{2}\alpha - 6\sqrt{2} > \frac{(\alpha+1)(2-\sqrt{2})}{\sqrt{2}\alpha + 2\sqrt{2} - 1}$ when $\alpha > \frac{12 - 9\sqrt{2} + \sqrt{378 + 216\sqrt{2}}}{36} = 0.6944$.
So we find for $\alpha \in (\alpha_1, \alpha_2]$ that

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} < 9\sqrt{2}\alpha - 6\sqrt{2}.$$

3.1.2. Even case with $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$ and $q \geq 6$

For the remainder of this section we assume $q \geq 6$. The shape of the region $\mathcal{D} \subset \Omega_\alpha$, where $\min\{\Theta_{n-1}, \Theta_n\} > \frac{1}{2}$ is given in the next lemma; see Figure 3.

LEMMA 35. *For $\alpha \in (\frac{1}{2}, \frac{\lambda^2 + 4\lambda - 4}{2\lambda^3}]$ the region $\mathcal{D}$ consists of two components $\mathcal{D}_1$ and $\mathcal{D}_2$. The subregion $\mathcal{D}_1$ is bounded by the lines $t = l_0, v = H_1$ and the graph of f; $\mathcal{D}_2$ is bounded by the graph of g from the right, by the graph of f from below and by the boundary of Ω_α.*

If $\alpha \in (\frac{\lambda^2 + 4\lambda - 4}{2\lambda^3}, \frac{-\lambda^2 + 4\lambda + 4}{8\lambda}]$, then $\mathcal{D}_2$ splits into two parts and $\mathcal{D}$ consists of three components.

If $\alpha \in (\frac{-\lambda^2 + 4\lambda + 4}{8\lambda}, \frac{1}{\lambda})$, then $\mathcal{D}$ consists of four components: $\mathcal{D}_1$, the two parts of $\mathcal{D}_2$ and an additional part $\mathcal{D}_3$, bounded by the line $t = r_{p-1}$, the graph of g and the line $v = H_{2p-2}$; see Figure 4.
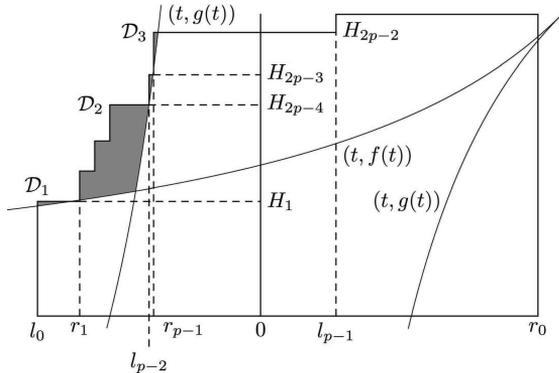

FIGURE 3. Sketch of $\mathcal{D}$ in Ω_α. The number of steps on the left boundary of $\mathcal{D}_2$ is about $p - 4$. In this figure we took $\alpha \in \left(\frac{-\lambda^2 + 4\lambda + 4}{8\lambda}, \frac{1}{\lambda}\right)$, so $\mathcal{D}_2$ is split into two components and there is a region $\mathcal{D}_3$.

P r o o f. Recall that $\mathcal{H}_q = \frac{1}{2}$. First assume $t \geq 0$. Arguing as in the case of $q = 4$, when $t \geq 0$ we have $\min\{\Theta_{n-1}, \Theta_n\} < \frac{1}{2}$.

Assume $t < 0$. The graph of $f(t)$ intersects the line $v = H_1$ in the point $(-H_{2p-3}, H_1)$, but also that

$$l_0 < -H_{2p-3} < r_1 \quad \text{if } \alpha < \frac{1}{\lambda}.$$

Since the function $f(t)$ is strictly increasing and $f(0) = \mathcal{H}_q < \frac{1}{\lambda} = H_2$, it follows that the graph of $f(t)$ does not intersect any of the line segments $v = H_i$ for $i = 2, \ldots, 2p - 2$ for $t < 0$.

Next we consider the intersection points of the graph of $g(t)$ with the line segments $v = H_i$ for $i = 1, \ldots, 2p-2$. We work from right to left. The intersection point of the graph of g and the line $v = H_{2p-2} = \frac{\lambda}{2}$ is given by $(\frac{-2}{\lambda+4}, \frac{\lambda}{2})$. The first coordinate of this point is larger than r_{p-1} if and only if $\alpha > \frac{-\lambda^2+4\lambda+4}{8\lambda}$ and always smaller than l_{p-1}, since $l_{p-1} > 0$. We conclude that $\frac{-2}{\lambda+4} \in J_{2p-2}$ if and only if

$$\alpha \in \left(\frac{-\lambda^2 + 4\lambda + 4}{8\lambda}, \frac{1}{\lambda} \right).$$

The intersection point of the graph of $g(t)$ with the line $v = H_{2p-3} = \lambda - 1$ is given by $(-H_1, H_{2p-3})$. Since $-\delta_1 < -H_1 < r_{p-1}$, we have by Theorem 22 that $-H_1 \in J_{2p-3}$ for all $\alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$.

Furthermore,

$$g(l_{p-2}) = -2 - \frac{(-\alpha\lambda^2 + 2\alpha + 1)\lambda}{\alpha\lambda^2 - 2}$$

and we find that

$$g(l_{p-2}) > H_{2p-4} = \lambda - \frac{2}{\lambda} \quad \text{if and only if} \quad \alpha > \frac{\lambda^2 + 4\lambda - 4}{2\lambda^3},$$

So if $\alpha \in (\frac{\lambda^2+4\lambda-4}{2\lambda^3}, \frac{1}{\lambda})$, then $\mathcal{D}_2$ consists of two separated parts.

The graph of $g(t)$ does not intersect any of the other lines $v = H_i$ with $i = 1, \ldots, 2p - 5$, since g is strictly increasing and

$$g(r_{p-2}) = -2 - \frac{1}{r_{p-2}} = -2 + \lambda + r_{p-1} < 0,$$

where we used that $r_{p-2} = \frac{-1}{\lambda+r_{p-1}}$, $\lambda < 2$ and $r_{p-1} < 0$. $\quad\square$

We see that $\mathcal{D}$ stretches over several intervals J_n, which was not the case for $q = 4$. Points (t_n, v_n) in $\mathcal{D}_1$ have $t_n \in J_1 = [l_0, r_1)$, points in $\mathcal{D}_2$ have $t_n \in J_2 \cup \cdots \cup J_{2p-1} = [r_1, r_{p-1})$ and points in $\mathcal{D}_3$ have $t_n \in J_{2p-2} = [r_{p-1}, l_{p-1}]$.

On $\mathcal{D}$ we consider Θ_{n+1}, the "next" approximation coefficient. We wish to express Θ_{n+1} locally as a function of only t_n and v_n. We divide $\mathcal{D}$ into subregions where $d_{n+1}, \varepsilon_{n+1}$ and ε_{n+2} are constant. This gives three regions; see Table 1 for the definition of the subregions.

TABLE 1. Subregions of $\mathcal{D}$ giving constant coefficients.

Region							d_{n+1}	ε_{n+1}	ε_{n+2}
(I)	$\left\{ (t_n, v_n) \right.$	$\in$	$\mathcal{D}$	l_0	$\leq$	$\left. t_n < \frac{-1}{\lambda} \right\}$	1	-1	-1
(II)	$\left\{ (t_n, v_n) \right.$	$\in$	$\mathcal{D}$	$\frac{-1}{\lambda}$	$\leq$	$\left. t_n < -\delta_1 \right\}$	1	-1	1
(III)	$\left\{ (t_n, v_n) \right.$	$\in$	$\mathcal{D}$	$-\delta_1$	$\leq$	$\left. t_n < \frac{-1}{2\lambda} \right\}$	2	-1	-1

We analyse Θ_{n+1} on the three regions.

Region(I)

On Region (I) we have that $\Theta_{n+1} < \frac{1}{2}$ if and only if $v_n > \frac{2\lambda t_n + 2\lambda + 1}{2\lambda t_n - t_n + 2}$.

Region(II)

Region (II) is mapped to Ω_α^+ under $\mathcal{T}_\alpha$, so on Region (II) $\Theta_{n+1} < \frac{1}{2}$ for all points (t_n, v_n).

Region(III)

We denote the intersection of $\mathcal{D}_2$ and Region (III) by $\mathcal{A}$. The vertices of $\mathcal{A}$ are given by $\left(-\delta_1, g(-\delta_1)\right)$, $(\frac{-1}{\lambda+1}, \lambda - 1)$ and $(-\delta_1, \lambda - 1)$. The vertices of $\mathcal{D}_3$ are given by $\left(r_{p-1}, g(r_{p-1})\right)$, $(\frac{-2}{\lambda+4}, \frac{\lambda}{2})$ and $(r_{p-1}, \frac{\lambda}{2})$. See Figure 4.

We focus on Region (III) and discuss points in Region (I) later.

We want to determine bounds for the minimum of three consecutive approximation coefficients on $\mathcal{A}$ and $\mathcal{D}$.

LEMMA 36. *For each point (t_n, v_n) in Region* (III)
$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} = \Theta_n.$$

P r o o f. On region (III) it holds that $v_n > -t_n$, so from (16) it immediately follows that
$$\Theta_{n-1} > \Theta_n.$$

Using (18) we find that $\Theta_{n+1} > \Theta_n$ if and only if $v_n < \frac{(4\lambda^2-1)t_n + 2\lambda}{2\lambda t_n + 1}$. Put $v(t) = \frac{(4\lambda^2-1)t + 2\lambda}{2\lambda t + 1}$. This function is decreasing in t for $t < \frac{-1}{2\lambda}$. We find that
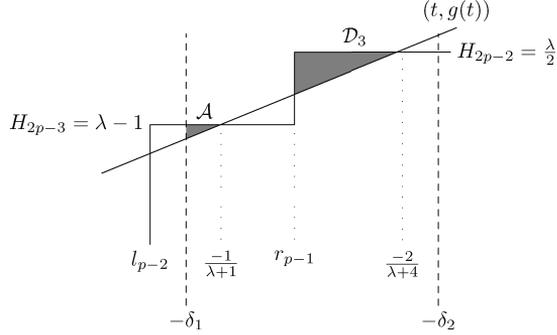
FIGURE 4. Region (III) in Ω_α. If $\alpha < \frac{-\lambda^2 + 4\lambda + 4}{8\lambda}$ there is no region $\mathcal{D}_3$.

$v(\frac{-2}{\lambda+4}) > 1$ if and only if $\lambda > \frac{11+\sqrt{73}}{12}$. This last inequality is satisfied for all λ_q with $q \geq 6$. $\qquad\square$

COROLLARY 37. *For each point (t_n, v_n) in Region* (III)

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n-1}\} > \frac{1}{2}.$$

It follows that for every point (t_n, v_n) in Region (III) we have

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} \leq \max_{(t,v)\in \text{ Region (III)}} \Theta_n(t,v).$$

The partial derivatives of Θ_n on Region (III) are given by

$$\frac{\partial \Theta_n}{\partial t_n} = \frac{-1}{(1 + t_n v_n)^2} < 0 \quad \text{and} \quad \frac{\partial \Theta_n}{\partial v_n} = \frac{t_n^2}{(1 + t_n v_n)^2} > 0.$$

We find that Θ_n takes its maximum on $\mathcal{A}$ in the upper left corner, the point $(-\delta_1, H_{2p-3})$, and on $\mathcal{D}_3$ in the vertex (r_{p-1}, H_{2p-2}). Using (26) we find that these maxima are given by

$$\begin{aligned}
\Theta_n(-\delta_1, \lambda - 1) &= \frac{\delta_1}{1 - \delta_1(\lambda - 1)} = \frac{1}{\alpha\lambda + 1}, \\
\Theta_n\left(r_{p-1}, \frac{\lambda}{2}\right) &= \frac{-r_{p-1}}{1 + \frac{r_{p-1}\lambda}{2}} = \frac{2\lambda(2\alpha - 1)}{4 - \lambda^2}.
\end{aligned}$$

We find that

$$\Theta_n(-\delta_1, \lambda - 1) > \Theta_n\left(r_{p-1}, \frac{\lambda}{2}\right) \quad \text{if and only if} \quad \alpha < \frac{\lambda - 2 + \sqrt{-3\lambda^2 + 4\lambda + 20}}{4\lambda}.$$

For all $\lambda < 2$ we have $\frac{-\lambda^2+4\lambda+4}{8\lambda} < \frac{\lambda-2+\sqrt{-3\lambda^2+4\lambda+20}}{4\lambda} < \frac{1}{\lambda}$.

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COROLLARY 38. *For every point (t_n, v_n) in Region (III)*

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}\} \leq \begin{cases} \frac{1}{\alpha\lambda+1} & \text{if } \alpha \in \left(\frac{1}{2}, \frac{\lambda-2+\sqrt{-3\lambda^2+4\lambda+20}}{4\lambda}\right], \\ \frac{2\lambda(2\alpha-1)}{4-\lambda^2} & \text{if } \alpha \in \left(\frac{\lambda-2+\sqrt{-3\lambda^2+4\lambda+20}}{4\lambda}, \frac{1}{\lambda}\right). \end{cases}$$

Orbit of points in Region (III)

We study the orbit of points in $\mathcal{A}$ and $\mathcal{D}_3$ to derive the spectrum for α-Rosen fractions. We call $p-1$ consecutive applications of $\mathcal{T}_\alpha$ a *round*. We use Möbius transformations to find an explicit formula for $\mathcal{T}_\alpha^{p-1}$; see [7] for background, or [13], where such techniques are used. Let S and T be the generating matrices of the group G_q

$$S = \begin{bmatrix} 1 & \lambda \\ 0 & 1 \end{bmatrix} \quad \text{and} \quad T = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}. \tag{39}$$

Recall that in this context we consider matrices M and $-M$ to be equivalent. Elementary calculations and formula (7) yield the following result.

LEMMA 40. *Let $(t, v) \in \Omega_\alpha$ be given. Put*

$$d = d(t), \ \varepsilon = \varepsilon(t) \quad \text{and} \quad A = \begin{bmatrix} -d\lambda & \varepsilon \\ 1 & 0 \end{bmatrix}.$$

Then

$$\mathcal{T}_\alpha(t, v) = \big(A(t), TAT(v)\big).$$

Furthermore, we have the following lemma.

LEMMA 41. *Put $\mathcal{M} = (S^{-1}T)^{p-2} S^{-2}T$. For $(t, v) \in \mathcal{A} \cup \mathcal{D}_3$ we have*

$$\mathcal{T}_\alpha^{p-1}(t, v) = \big(\mathcal{M}(t), T\mathcal{M}T(v)\big).$$

P r o o f. First assume $(t, v) \in \mathcal{A}$, so $-\delta_1 \leq t \leq \frac{-1}{\lambda+1} < -\delta_2$. We have

$$\varepsilon(t) = -1 \quad \text{and} \quad d(t) = 2, \quad \text{and} \quad T_\alpha(t) = \frac{-1}{t} - 2\lambda.$$

We note that

$$S^{-2}T(t) = \begin{bmatrix} -2\lambda & -1 \\ 1 & 0 \end{bmatrix}(t) = \frac{-1}{t} - 2\lambda.$$

We find

$$T_\alpha(-\delta_1) = (\alpha - 1)\lambda = l_0 \quad \text{and} \quad T_\alpha\left(\frac{-1}{\lambda+1}\right) = 1 - \lambda = -H_{2p-3}.$$

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As noted in the proof of Lemma 35, one has $-H_{2p-3} < r_1$. From Theorem 22 and the above estimates it follows that for both $-\delta_1$ and r_{p-1} the following $p-2$ applications of T_α give $\varepsilon = -1$ and $d = 1$. Thus we use $p-2$ times

$$T_\alpha(t) = \frac{-1}{t} - \lambda = \frac{-\lambda t - 1}{t} = \begin{bmatrix} -\lambda & -1 \\ 1 & 0 \end{bmatrix}(t) = V(t).$$

Combining the first step with these $p-2$ steps we find $\mathcal{M} = (S^{-1}T)^{p-2}S^{-2}T$ for points $(t, v) \in \mathcal{A}$. From Lemma 40 and the fact that $TT = I$ we find that the second coordinate is given by $T\mathcal{M}T$.

Now assume $(t, v) \in \mathcal{D}_3$. In this case $\alpha \in (\frac{-\lambda^2 + 4\lambda + 4}{8\lambda}, \frac{1}{\lambda})$ and $-\delta_1 < r_{p-1} \leq t \leq \frac{-2}{\lambda+4} < -\delta_2$. We again have $\varepsilon(t) = -1$ and $d(t) = 2$, and find

$$T_\alpha(r_{p-1}) = \frac{2 + \lambda^2(1 - 3\alpha)}{(2\alpha - 1)\lambda} = r_p \quad \text{and} \quad T_\alpha\left(\frac{-2}{\lambda+4}\right) = 2 - \frac{3\lambda}{2}.$$

For $\alpha \in \left(\frac{-\lambda^2 + 4\lambda + 4}{8\lambda}, \frac{1}{\lambda}\right)$ we have $r_p < 2 - \frac{3\lambda}{2} < l_1$, so like before we apply T_α in the next $p-2$ steps with $\varepsilon = -1$ and $d = 1$. $\qquad\square$

We use the auxiliary sequence B_n from (12) and induction to find powers of $S^{-1}T$.

LEMMA 42. *For $n \geq 1$ we have*

$$(S^{-1}T)^n = \begin{bmatrix} -B_{n+1} & -B_n \\ B_n & B_{n-1} \end{bmatrix}.$$

Using (13), Lemmas 41 and 42, and some easy calculations we find the following lemma. (The proof is given in [18], like any other suppressed proof in this paper.)

LEMMA 43. *The function $\mathcal{T}_\alpha^{p-1}$ is explicitly given by*

$$\mathcal{T}_\alpha^{p-1}(t, v) = \frac{B_p}{2}\left(\begin{bmatrix} -\lambda^2 - 2 & -\lambda \\ \lambda^3 - \lambda & \lambda^2 - 2 \end{bmatrix}(t), \begin{bmatrix} -\lambda^2 + 2 & \lambda^3 - \lambda \\ -\lambda & \lambda^2 + 2 \end{bmatrix}(v)\right).$$

With the explicit fomula for $\mathcal{M}(t)$ we can easily compute its fixed points, they are given by

$$t_1 = \frac{-1}{\lambda + 1} \quad \text{and} \quad t_2 = \frac{-1}{\lambda - 1}.$$

The fixed points of $T\mathcal{M}T(v)$ are given by

$$v_1 = \lambda + 1 \quad \text{and} \quad v_2 = \lambda - 1.$$

COROLLARY 44. *The point $(\frac{-1}{\lambda+1}, \lambda - 1)$ is a fixed point of $\mathcal{T}_\alpha^{p-1}(t, v)$.*

REMARK 45. If $\varepsilon = -1$ and d is constant, then $T_\alpha(t)$ is strictly increasing in t. From this and the above corollary we find that for $(t, v) \in \mathcal{A}$ we have $\mathcal{M}(t) \leq t$, whilst for points $(t, v) \in \mathcal{D}_3$ we have $\mathcal{M}(t) > t$.

Flushing

We say a point is *flushed* when it is mapped from $\mathcal{D}$ to a point outside of $\mathcal{D}$ by $\mathcal{T}_\alpha$. We look at the flushing of points in $\mathcal{A}$ and $\mathcal{D}_3$.

Flushing from $\mathcal{A}$

Combining all the above we find that the vertices of $\mathcal{A}$ are mapped as follows under $\mathcal{T}^{p-1}$.

$$(-\delta_1, \lambda - 1) \quad \mapsto \quad \left(\frac{\alpha\lambda^2 - 2}{(-\alpha\lambda^2 + 2\alpha + 1)\lambda}, \lambda - 1 \right) = (l_{p-2}, \lambda - 1)$$

$$\left(\frac{-1}{\lambda + 1}, \lambda - 1 \right) \quad \mapsto \quad \left(\frac{-1}{\lambda + 1}, \lambda - 1 \right),$$

$$(-\delta_1, g(-\delta_1)) \quad \mapsto \quad \left(l_{p-2}, \lambda - \frac{(2\alpha - 1)\lambda - 4}{(\alpha\lambda - 2)\lambda - 2} \right).$$
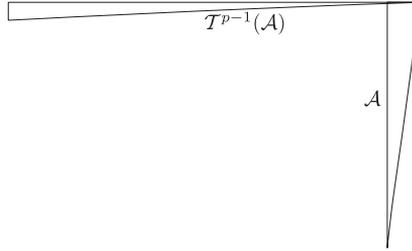

FIGURE 5. $\mathcal{A}$ and its $(p-1)$st transformation under $\mathcal{T}_\alpha$.

The image of $\mathcal{A}$ under $\mathcal{T}_\alpha^{p-1}$ is a long, thin "triangle" that has a "triangular" intersection with $\mathcal{A}$; see Figure 5. We notice in particular that $(-\delta_1, H_{2p-3})$ is included in $\mathcal{T}_\alpha^{p-1}(\mathcal{A})$. However, the part of $\mathcal{T}_\alpha^{p-1}(\mathcal{A})$ on the left-hand side of the line $t = -\delta_1$ is in Region (II). So these points are flushed in the next application of $\mathcal{T}_\alpha$.

We conclude that for the points $(t_n, v_n) \in \mathcal{A}$ with $T_\alpha^{p-1}(t_n) < -\delta_1$ we have

$$\min\{\Theta_{n-1}, \Theta_n, \Theta_{n+1}, \ldots, \Theta_{n+p-1} > \mathcal{H}_q\} \quad \text{and} \quad \Theta_{n+p} < \mathcal{H}_q.$$

The following theorem generalizes this idea to multiple rounds. Recall from formula (23) that we define τ_k by

$$(\tau_k, \nu_k) = \mathcal{T}_\alpha^{-k(p-1)}(-\delta_1, H_1).$$

THEOREM 46. *Let $k \geq 1$ be an integer.*

Any point (t, v) of $\mathcal{A}$ is flushed after exactly k rounds if and only if

$$\tau_{k-1} \leq t < \tau_k.$$

For any x with $\tau_{k-1} \leq t_n < \tau_k$,

$$\min\left\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(p-1)-1}, \Theta_{n+k(p-1)}\right\} > \mathcal{H}_q,$$

while

$$\Theta_{n+k(p-1)+1} < \mathcal{H}_q.$$

P r o o f. A point $(t, v) \in \mathcal{A}$ is flushed after exactly k rounds if k is minimal such that $\mathcal{T}_\alpha^{k(p-1)}(t, v)$ has its first coordinate smaller than $-\delta_1$. The result follows from the definition of τ_k and the above. $\qquad\square$

Flushing from $\mathcal{D}_3$

Recall that the vertices of $\mathcal{D}_3$ are given by $\left(r_{p-1}, g(r_{p-1})\right)$, $\left(\frac{-2}{\lambda+4}, \frac{\lambda}{2}\right)$ and $\left(r_{p-1}, \frac{\lambda}{2}\right)$; see Figure 4. We have $\frac{-1}{\lambda+1} < r_{p-1} < \frac{-2}{\lambda+4}$ and $\lambda - 1 < g(r_{p-1}) < \frac{\lambda}{2}$. The fixed point $\left(\frac{-1}{\lambda+1}, \lambda - 1\right)$ of $\mathcal{T}^{p-1}$ is repelling in the t-direction and attractive in the v-direction.

LEMMA 47. *There exists a positive integer K such that all points in $\mathcal{D}_3$ are flushed after K rounds.*

P r o o f. Let $(t_1, \lambda - 1 + v_1)$ be a point in $\mathcal{D}_3$, it follows that $0 < v_1 < 1$. With Lemma 43 we find for the second coordinate

$$\pi_2\left(\mathcal{T}_\alpha^{p-1}(t_1, \lambda - 1 + v_1)\right) = \frac{(-\lambda^2 + 2)(\lambda - 1 + v_1) + \lambda^3 - \lambda}{-\lambda(\lambda - 1 + v_1) + \lambda^2 + 2} = \lambda - 1 + \frac{2 - \lambda}{\lambda + 2 - \lambda v_1} v_1.$$

As $\frac{2-\lambda}{\lambda+2-\lambda v_1} < 1 - \frac{\lambda}{2} < 1$, the result follows. $\qquad\square$

REMARK 48. We could divide $\mathcal{D}_3$ in parts that get flushed after $1, 2, \ldots, K$ rounds, respectively. As we saw in the example for $q = 4$ the formulas needed to do this are rather ugly and in this general case they only get worse. For our main result we only need that after finitely many rounds all points are flushed out of $\mathcal{D}_3$.

We still need to consider points in Region (I). It follows from Theorem 22 that after at most $p - 2$ steps each such point is either flushed or mapped into $\mathcal{A} \cup \mathcal{D}_3$. We are now ready to prove Theorem 24 for this case.

P r o o f   o f   T h e o r e m   24   f o r $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$. By definition $\tau_k < \tau_{k+1}$. In [3] it was shown that $\frac{-1}{\lambda+1} = \overline{[(-1 : 2), (-1 : 1)^{p-2}]}$ and we find $\lim_{k \to \infty} \tau_k = \frac{-1}{\lambda+1}$. Recall that $c_k = \frac{-\tau_{k-1}}{1+\tau_{k-1}\nu_{k-1}}$. It follows that $c_{k+1} < c_k$ and $\lim_{k \to \infty} c_k = \frac{1}{2}$.

Take an integer k such that $k > K$ by Lemma 47. Take a point $(t_n, v_n) \in \mathcal{D}$ that did not get flushed in the first $k - 1$ rounds. There exists an index i with $0 \leq i \leq p - 2$ such that (t_{n+i}, v_{n+i}) is either in $\mathcal{A}$ or is flushed. We assume $(t_{n+i}, v_{n+i}) \in \mathcal{A}$, otherwise we are done. From Theorem 46 we find that $t_{n+i} \geq \tau_k$. Thus $\Theta_n(t_{n+i}, v_{n+i}) \leq \Theta_n(\tau_{k-1}, \lambda - 1) = c_k$. $\qquad\square$

3.2. Even case for $\alpha = \frac{1}{\lambda}$

The natural extension $\Omega_{1/\lambda}$ can be found from $\Omega_{1/2}$ by reflecting in the line $v = -t$ if $t \leq 0$, and in the line $v = t$ if $x \geq 0$; see [DKS].

In the case $\alpha = \frac{1}{2}$ we have $l_n = r_n$ for $n \geq 1$; see Theorem 22. We put $\varphi_0 = l_0 = -\frac{\lambda}{2}$ and denote $\varphi_n = l_n = r_n = T_{1/2}^n(\varphi_0)$. Put

$$L_1 = \frac{1}{\lambda + 1} \quad \text{and} \quad L_n = \frac{1}{\lambda - L_{n-1}} \quad \text{for} \quad n = 2, 3, \ldots, p - 1.$$

We know from [5] that

$$\Omega_{1/2} = \left(\bigcup_{n=1}^{p-1} [\varphi_{n-1}, \varphi_n) \times [0, L_n] \right) \cup [0, -\varphi_0) \times [0, 1],$$

$$\Omega_{1/\lambda} = \left(\bigcup_{n=1}^{p-2} [-L_{p-n}, -L_{p-n-1}) \times [0, -\varphi_{p-n-1}] \right) \cup [-L_1, 1) \times [0, -\varphi_0],$$

see Figure 6 for an example with $q = 8$.

We now could proceed as in the previous two subsections; For $t \geq 0$ one easily sees that the graphs of f and g do not meet in $\Omega_{1/\lambda}$ (they meet in $(1, 1)$, which is outside $\Omega_{1/\lambda}$). As before, from this it follows that for $t_n \geq 0$ we have that $\min\{\Theta_{n-1}, \Theta_n\} < \frac{1}{2}$. So we only need to focus on the region $\mathcal{D}$, and how it is eventually "flushed." However, we can also derive the result directly from the case $\alpha = \frac{1}{2}$.

Define the map $M : \Omega_{1/\lambda} \to \Omega_{1/2}$ by

$$M(t, v) = \begin{cases} (-v, -t) & \text{if } t < 0, \\ (v, t) & \text{if } t \geq 0. \end{cases} \tag{49}$$
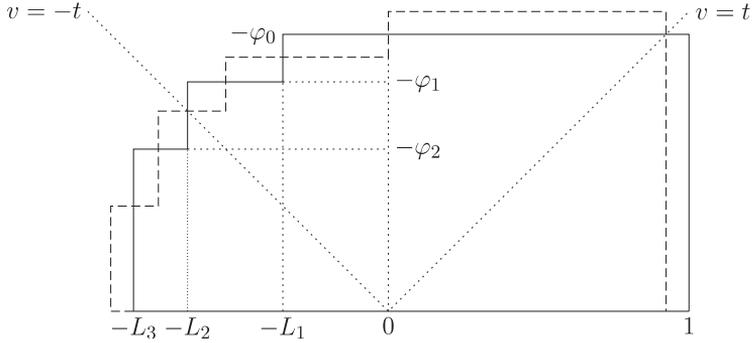
FIGURE 6. We find $\Omega_{\frac{1}{\lambda}}$ by reflecting $\Omega_{\frac{1}{2}}$ (dashed) in $v = |t|$. In this example $q = 8$.

In [5] it was shown that

$$\mathcal{T}_{1/\lambda}(t, v) = M^{-1}\left(\mathcal{T}_{1/2}^{-1}(M(t, v))\right). \qquad (50)$$

This implies that the dynamical systems

$$(\Omega_{1/2}, \mu_{1/2}, \mathcal{T}_{1/2}) \quad \text{and} \quad (\Omega_{1/\lambda}, \mu_{1/\lambda}, \mathcal{T}_{1/\lambda})$$

are isomorphic. These systems "behave dynamically in the same way," also see [14]. Usually, this is not much of help if we want to obtain Diophantine properties of one system from the other system. But the special form of the isomorphism M makes it possible to prove directly that these systems posses the same "Diophantine properties." Essentially, if one "moves forward in time" in $(\Omega_{1/2}, \mu_{1/2}, \mathcal{T}_{1/2})$, then one "moves backward in time" in $(\Omega_{1/\lambda}, \mu_{1/\lambda}, \mathcal{T}_{1/\lambda})$ and vice versa.

THEOREM 51. *Let $\ell \in \mathbb{N}$, and let $\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+\ell}$ be $\ell + 2$ consecutive approximation coefficients of the point $(t_n, v_n) \in \Omega_{1/\lambda}$, then there exists a point $(\tilde{t}_m, \tilde{v}_m) \in \Omega_{1/2}$ and approximation coefficients $\tilde{\Theta}_m, \tilde{\Theta}_{m-1}, \ldots, \tilde{\Theta}_{m-\ell-1}$, given by*

$$\tilde{\Theta}_m = \Theta_m(\tilde{t}_m, \tilde{v}_m) = \frac{|\tilde{t}_m|}{1 + \tilde{t}_m \tilde{v}_m}, \quad \tilde{\Theta}_{m-1} = \Theta_{m-1}(\tilde{t}_m, \tilde{v}_m) = \frac{\tilde{v}_m}{1 + \tilde{t}_m \tilde{v}_m}, \ldots,$$

$$\tilde{\Theta}_{m-\ell-1} = \Theta_{m-\ell-1}(\tilde{t}_{m-\ell}, \tilde{v}_{m-\ell}) = \frac{\tilde{v}_{m-\ell}}{1 + \tilde{t}_{m-\ell} \tilde{v}_{m-\ell}},$$

such that

$$\Theta_{n-1} = \tilde{\Theta}_m, \ \Theta_n = \tilde{\Theta}_{m-1}, \ \Theta_{n+1} = \tilde{\Theta}_{m-2}, \ \ldots, \ \Theta_{n+\ell} = \tilde{\Theta}_{m-\ell-1}. \qquad (52)$$

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P r o o f. Let $(\tilde{t}_m, \tilde{v}_m) = M(t_n, v_n) \in \Omega_{1/2}$ be the point in $\Omega_{1/2}$ corresponding to $(t_n, v_n) \in \Omega_{1/\lambda}$ under the isomorphism M from (49). Then

$$(\tilde{t}_m, \tilde{v}_m) = \begin{cases} (-v_n, -t_n) & \text{if } t_n < 0, \\ (v_n, t_n) & \text{if } t_n \geq 0, \end{cases}$$

and we find that

$$\tilde{\Theta}_{m-1} = \Theta_{m-1}(\tilde{t}_m, \tilde{v}_m) = \frac{\tilde{v}_m}{1 + \tilde{t}_m \tilde{v}_m} = \frac{|t_n|}{1 + t_n v_n} = \Theta_n.$$

Similarly,

$$\tilde{\Theta}_m = \Theta_m(\tilde{t}_m, \tilde{v}_m) = \frac{|\tilde{t}_m|}{1 + \tilde{t}_m \tilde{v}_m} = \frac{v_n}{1 + t_n v_n} = \Theta_{n-1}.$$

So we have $(\Theta_{n-1}, \Theta_n) = (\tilde{\Theta}_m, \tilde{\Theta}_{m-1})$.

Furthermore, by (50) we have

$$\begin{aligned} (t_{n+1}, v_{n+1}) &= \mathcal{T}_{1/\lambda}(t_n, v_n) = M^{-1}\left(\mathcal{T}_{1/2}(M(t_n, v_n))\right) \\ &= M^{-1}\left(\mathcal{T}_{1/2}(\tilde{t}_m, \tilde{v}_m)\right) = M^{-1}(\tilde{t}_{m-1}, \tilde{v}_{m-1}), \end{aligned}$$

and we see that

$$(\tilde{t}_{m-1}, \tilde{v}_{m-1}) = M(t_{n+1}, v_{n+1}) = \begin{cases} (-v_{n+1}, -t_{n+1}) & \text{if } t_{n+1} < 0 \\ (v_{n+1}, t_{n+1}) & \text{if } t_{n+1} \geq 0. \end{cases}$$

But then we have

$$\tilde{\Theta}_{m-2} = \frac{\tilde{v}_{m-1}}{1 + \tilde{t}_{m-1} \tilde{v}_{m-1}} = \frac{|t_{n+1}|}{1 + t_{n+1} v_{n+1}} = \Theta_{n+1},$$

and by induction it follows that

$$\Theta_{n-1} = \tilde{\Theta}_m, \ \Theta_n = \tilde{\Theta}_{m-1}, \ \Theta_{n+1} = \tilde{\Theta}_{m-2}, \ \ldots, \ \Theta_{n+\ell} = \tilde{\Theta}_{m-\ell-1}.$$

$\square$

An immediate consequence of (16) is the following lemma.

LEMMA 53. *Let Θ_{n-1} and Θ_n be two consecutive approximation coefficients of the point (t_n, v_n). Then*

$$t_n = \frac{1 + \varepsilon_{n+1}\sqrt{1 - 4\varepsilon_{n+1}\Theta_{n-1}\Theta_n}}{2\Theta_{n-1}} \quad \text{and} \quad v_n = \frac{\varepsilon_{n+1} + \sqrt{1 - 4\varepsilon_{n+1}\Theta_{n-1}\Theta_n}}{2\Theta_n}.$$

P r o o f   o f   T h e o r e m   24   f o r $\alpha = 1/\lambda$. Let x be a G_q-irrational with $1/\lambda$--expansion $[\varepsilon_1 : d_1, \varepsilon_2 : d_2, \varepsilon_3 : d_3, \ldots]$ and let $n \geq 1$ be an integer. Assume there is a $k \in \mathbb{N}$ such that

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(p-1)}\} > \frac{1}{2},$$

otherwise we are done. From Lemma 53 we find the appropriate $(t_n, v_n) \in \Omega_{1/\lambda}$ for this sequence of approximation coefficients. From Theorem 51 if follows that we can find $(\tilde{t}_m, \tilde{v}_m) \in \Omega_{1/2}$ such that

$$\Theta_{n-1} = \tilde{\Theta}_m, \Theta_n = \tilde{\Theta}_{m-1}, \ldots, \Theta_{n+k(p-1)} = \tilde{\Theta}_{m-k(p-1)-1}.$$

It follows from Theorem 6 for $\alpha = \frac{1}{2}$ that

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(p-1)}\} = \min\{\tilde{\Theta}_{m-k(p-1)-1}, \ldots, \tilde{\Theta}_{m-1}, \tilde{\Theta}_m, \} < c_k,$$

where c_k is defined in (23) and Theorem 24. This proves Theorem 24 for the case $\alpha = 1/\lambda$. $\qquad\square$

4. Tong's spectrum for odd α-Rosen fractions

Let $q = 2h + 3$ for $h \geq 1$ and define

$$\rho = \frac{\lambda - 2 + \sqrt{\lambda^2 - 4\lambda + 8}}{2}. \tag{54}$$

We often use the following relations for ρ

$$\rho^2 + (2 - \lambda)\rho - 1 = 0 \quad \text{and} \quad \frac{\rho}{\rho^2 + 1} = \mathcal{H}_q = \frac{1}{\sqrt{\lambda^2 - 4\lambda + 8}}.$$

REMARK 55. For $q = 3$ (i.e. $\lambda = 1$) we are in the "classical" case of Nakada's α-expansions [16]. In this case $\frac{\rho}{\lambda} = \frac{\sqrt{5}-1}{2} = g$ and $\mathcal{H}_q = \frac{1}{\sqrt{5}}$; see also [9] for a discussion of this case.

For a fixed λ we define the following constants

$$\alpha_1 = \frac{(\lambda - 2)\mathcal{H}_q + 1}{\lambda},$$

$$\alpha_2 = \frac{-\lambda + \sqrt{5\lambda^2 - 4\lambda + 4}}{2\lambda},$$

$$\alpha_3 = \frac{(2 - \lambda)^2 \mathcal{H}_q + 2\lambda}{4\lambda},$$

$$\alpha_4 = \frac{(2 - \lambda)\mathcal{H}_q - 2}{(\lambda\mathcal{H}_q - 2\mathcal{H}_q - 2)\lambda}.$$

For all admissible λ we have

$$\frac{1}{2} < \alpha_1 < \alpha_2 < \alpha_3 < \frac{\rho}{\lambda} < \alpha_4 < \frac{1}{\lambda}. \tag{56}$$

REMARK 57. These numbers are very near to each other. For example, if $q = 9$,

$$\alpha_1 \approx 0.500058, \qquad \alpha_2 \approx 0.500515, \qquad \alpha_3 \approx 0.500966$$

$$\frac{\rho}{\lambda} \approx 0.500967, \qquad \alpha_4 \approx 0.500994, \qquad \frac{1}{\lambda} \approx 0.532089.$$

In [5] it was shown that there are four subcases for the natural extension of odd α-Rosen fractions: $\alpha = \frac{1}{2}, \alpha \in \left(\frac{1}{2}, \frac{\rho}{\lambda}\right), \alpha = \frac{\rho}{\lambda}$ and $\alpha \in \left(\frac{\rho}{\lambda}, \frac{1}{\lambda}\right]$. Again, the case $\alpha = \frac{1}{2}$ had been dealt with in [13] and we give the details for the other cases in this section.

The following theorem from [5] is the counterpart for the odd case of Theorem 22.

THEOREM 58. *Let $q = 2h + 3, h \in \mathbb{N}, h \geq 1$. We have the following cases.*

$\alpha = \frac{1}{2}$:
$l_0 < r_{h+1} = l_{h+1} < r_1 = l_1 < \ldots < r_{h+n} = l_{h+n} < r_n = l_n < \ldots < r_{2h-1} = l_{2h-1} < r_{h-1} = l_{h-1} < r_{2h} = l_{2h} < -\delta_1 < r_h = l_h < -\delta_2 < r_{2h+1} = l_{2h+1} = 0 < r_0.$

$\frac{1}{2} < \alpha < \frac{\rho}{\lambda}$:
$l_0 < r_{h+1} < l_{h+1} < r_1 < l_1 < \ldots < r_{h+n} < l_{h+n} < r_n < l_n < \ldots < r_{2h-1} < l_{2h-1} < r_{h-1} < l_{h-1} < r_{2h} < l_{2h} < -\delta_1 < r_h < l_h < r_{2h+1} < 0 < l_{2h+1} < r_0.$
Furthermore, we have $l_h < -\delta_2, l_{2h+2} = r_{2h+2}$ and $d_{2h+2}(r_0) = d_{2h+2}(l_0) + 1$.

$\alpha = \frac{\rho}{\lambda}$:
$l_0 = r_{h+1} < l_{h+1} = r_1 < \ldots < l_{n-1} = r_{h+n} < l_{h+n} = r_n < \ldots < l_{h-1} = r_{2h} < l_{2h} = r_h = -\delta_1 < l_h = r_{2h+1} < -\delta_2 < 0 < r_0.$

$\frac{\rho}{\lambda} < \alpha < \frac{1}{\lambda}$:
$l_0 < r_1 < l_1 < r_2 < \ldots < l_{h-1} < r_h < -\delta_1 < l_h < 0 < r_{h+1} < r_0.$
Furthermore, we have $l_{h+1} = r_{h+2}$ and $d_{h+1}(l_0) = d_{h+2}(r_0) + 1$.

$\alpha = \frac{1}{\lambda}$:
$l_0 = r_1 < l_1 = r_2 < \ldots < l_{h-1} = r_h < -\delta_1 < l_h = 0 = r_{h+1} < r_0.$

REMARK 59. In a preliminary version of [5] there was a small error in the above theorem in the case $\frac{1}{2} < \alpha < \frac{\rho}{\lambda}$: it stated that $-\delta_2 < r_{2h+1}$. But this is only true

if $\alpha < \alpha_2$. For all $\frac{1}{2} < \alpha < \frac{\rho}{\lambda}$ one has $r_{2h+1} = -\frac{(2\alpha-1)\lambda}{\alpha\lambda^2 - 2\lambda + 2}$, so

$$r_{2h+1} \geq -\delta_2 \Leftrightarrow -\frac{(2\alpha-1)\lambda}{\alpha\lambda^2 - 2\lambda + 2} \geq \frac{-1}{(\alpha+2)\lambda}$$

$$\Leftrightarrow \frac{-\lambda - \sqrt{5\lambda^2 - 4\lambda + 4}}{2\lambda} < \alpha \leq \frac{-\lambda + \sqrt{5\lambda^2 - 4\lambda + 4}}{2\lambda} = \alpha_2.$$

We conclude that $r_{2h+1} \geq -\delta_2$ if $\alpha \in \left(\frac{1}{2}, a_2\right)$ and that $r_{2h+1} < -\delta_2$ if $\alpha \in \left[a_2, \frac{\rho}{\lambda}\right)$.

In this section we prove the following result.

THEOREM 60. *Fix an odd $q = 2h + 3$, with $h \geq 1$.*

(i) Let $\alpha \in \left[\frac{1}{2}, \frac{\rho}{\lambda}\right]$. Then there exists a positive integer K such that for every G_q-irrational number x and all positive n and $k > K$,

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+k(2h+1)}\} < c_k,$$

for certain constants c_k with $c_{k+1} < c_k$ and $\lim_{k \to \infty} c_k = \mathcal{H}_q$.

(ii) Let $\alpha \in \left(\frac{\rho}{\lambda}, \frac{1}{\lambda}\right]$. For every G_q-irrational number x and all positive n, one has

$$\min\{\Theta_{n-1}, \Theta_n, \ldots, \Theta_{n+(3h+2)}\} < \mathcal{H}_q.$$

As Theorem 58 already suggests, the behavior of the dynamical system drastically changes at the point $\alpha = \rho/\lambda$. Case (i) is similar to the even case, but case (ii) yields a finite spectrum. We note such a finite spectrum was already described for the case $q = 3$ in [9].

For odd $q = 2h + 3$ we define a *round* by $2h+1$ consecutive applications of $\mathcal{T}_\alpha$.

Intersection of the graphs of $f(t)$ and $g(t)$

We start by looking at the behavior of the graphs of $f(t)$ and $g(t)$ as given in (19) on Ω_α for odd q.

In case $t > 0$ we find that

$$f(t) = g(t) \quad \text{if and only if} \quad t = \frac{1 \pm \sqrt{1 - 4\mathcal{H}_q^2}}{2\mathcal{H}_q}.$$

Since $\mathcal{H}_q < 1/2$,

$$\frac{1 + \sqrt{1 - 4\mathcal{H}_q^2}}{2\mathcal{H}_q} > 1 \geq \alpha\lambda$$

for all $\alpha \in [1/2, 1/\lambda]$, so we only need to consider $\frac{1 - \sqrt{1 - 4\mathcal{H}_q^2}}{2\mathcal{H}_q} = \rho$.
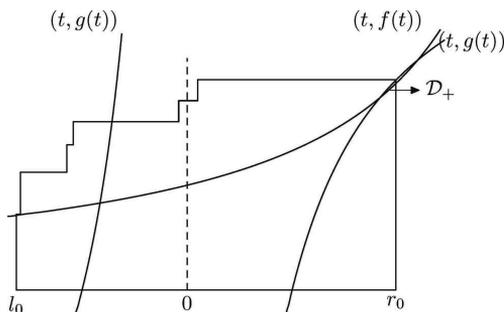
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FIGURE 7. For $\alpha > \rho/\lambda$ we have a part $\mathcal{D}^+$ for positive t.

Note that $f(\rho) = \rho$. In case

$$\alpha = \frac{1 - \sqrt{1 - 4\mathcal{H}_q^2}}{2\lambda\mathcal{H}_q} = \frac{\rho}{\lambda}, \tag{61}$$

we find that for $t > 0$ the intersection of the graphs of f and g is on the boundary of Ω_α, so if $\alpha \in [1/2, \rho/\lambda)$ we have that the intersection point for $t > 0$ is outside Ω_α, while for $\alpha \in (\rho/\lambda, 1/\lambda]$ it is inside Ω_α. Therefore, for the latter values of α we have an extra part $\mathcal{D}^+$ for positive t; see Figure 7. In this case we denote $\mathcal{D}^- = \{(x,y) \in \mathcal{D} \mid x \leq 0\}$ and $\mathcal{D}^+ = \{(x,y) \in \mathcal{D} \mid x > 0\}$.

4.1. Odd case for $\alpha \in (\frac{1}{2}, \frac{\rho}{\lambda})$

In this case the natural extension is given by $\Omega_\alpha = \bigcup_{n=1}^{4h+3} J_n \times [0, H_n]$, with

$$J_{4n-3} = [l_{n-1}, r_{h+n}), \quad J_{4n-2} = [r_{h+n}, l_{h+n}) \quad \text{for} \quad n = 1, \ldots, h+1,$$
$$J_{4n-1} = [l_{h+n}, r_n), \quad J_{4n} = [r_n, l_n) \quad \text{for} \quad n = 1, \ldots h,$$

and

$$H_1 = \frac{1}{\lambda + 1/\rho}, \quad H_2 = \frac{1}{\lambda + 1}, \quad H_3 = \frac{1}{\lambda + \rho}, \quad H_4 = \frac{1}{\lambda},$$
$$\text{and}$$
$$H_n = \frac{1}{\lambda - H_{n-4}} \quad \text{for} \quad n = 5, 6, \ldots, 4h+3.$$

In [5] it is shown that

$$H_{4h-1} = \lambda - \frac{1}{\rho}, \quad H_{4h} = \lambda - 1, \quad H_{4h+1} = \lambda - \rho \quad \text{and} \quad H_{4h+2} = \frac{\lambda}{2}.$$

Furthermore, from [5] we have that

$$l_h = \frac{1 - \alpha\lambda}{(\lambda - 1)\alpha\lambda - 1}, \quad r_h = -\frac{1 - (1 - \alpha)\lambda}{1 - (1 - \alpha)\lambda(\lambda - 1)} \quad \text{and} \quad r_{2h+1} = -\frac{(2\alpha - 1)\lambda}{\alpha\lambda^2 - 2\lambda + 2}.$$

We define $\mathcal{D}$ as in (21). We have proved above that in case $\alpha \leq \rho/\lambda$ we have $\mathcal{D}^+ = \emptyset$. We could divide $\mathcal{D}^-$ into regions where d_n, ε_{n+1} and ε_{n+2} are constant, as we did in Section 3.1.2. However, like before the region where $d_n = 2$ is the crucial one and we only describe the subregion of $\mathcal{D}^-$ that is on the right hand side of the line $t = -\delta_1$.
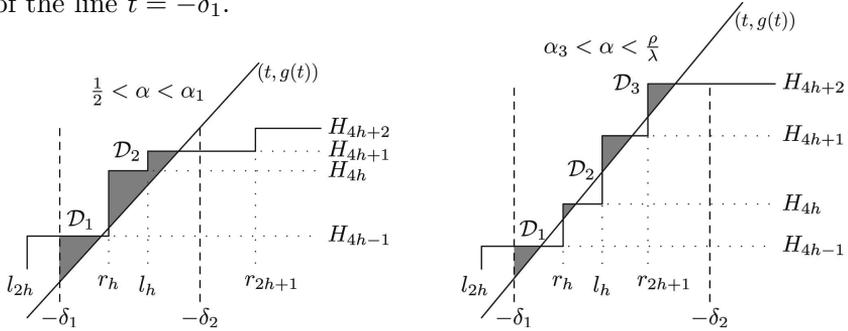

FIGURE 8. Schematic presentation of the part of $\mathcal{D}^-$ with $t > -\delta_1$ in two cases. If $\alpha_1 \leq \alpha < \alpha_2$, we have a similar picture as on the left: the only difference is that $\mathcal{D}_2$ is split into two components in this case. If $\alpha_2 < \alpha \leq \alpha_3$, the picture is similar to the one on the right, but there is no $\mathcal{D}_3$ in this case.

LEMMA 62. *If $\alpha \in \left(\frac{1}{2}, \alpha_1\right)$, then the subregion of $\mathcal{D}$ with $-\delta_1 < t < 0$ consists of two components: $\mathcal{D}_1$ bounded by the line $t = -\delta_1$ from the left, the line $v = H_{4h-1}$ from above and the graph of g from below. The second component $\mathcal{D}_2$ is bounded by line segments with $t = r_h, v = H_{4h}, t = l_h, v = H_{4h+1}$ and by the graph of g.*

If $\alpha \in [\alpha_1, \alpha_3]$, then $\mathcal{D}_1$ is as in the above case, but $\mathcal{D}_2$ is split into two components bounded by line segments as above and by the graph of g.

If $\alpha \in \left(\alpha_3, \frac{\rho}{\lambda}\right)$, then $\mathcal{D}_1$ and $\mathcal{D}_2$ are as in the previous case, but there is also a component $\mathcal{D}_3$, bounded by the line $t = r_{2h+1}$ from the left, the line $v = H_{4h+2}$ from above and the graph of g from below.

P r o o f. Recall that $H_{4h-1} = \lambda - \frac{1}{\rho}, H_{4h} = \lambda - 1, H_{4h+1} = \lambda - \rho$ and $H_{4h+2} = \frac{\lambda}{2}$. First of all $g(l_h) = -\frac{1}{\mathcal{H}_q} - \frac{1}{l_h} = -\frac{1}{\mathcal{H}_q} - \frac{(\lambda-1)\alpha\lambda-1}{1-\alpha\lambda}$ and we find

$$H_{4h-1} < g(l_h) < H_{4h} \qquad \text{if } \frac{1}{2} < \alpha < \alpha_1,$$

$$H_{4h} \leq g(l_h) < H_{4h+1} \qquad \text{if } \alpha_1 \leq \alpha < \frac{\rho}{\lambda}.$$

From $g(r_{2h+1}) = -\frac{1}{\mathcal{H}_q} + \frac{\alpha\lambda^2 - 2\lambda + 2}{(2\alpha - 1)\lambda}$ we find that

$$g(r_{2h+1}) > H_{4h+2} \quad \text{if and only if} \quad \alpha < \frac{(2-\lambda)^2 \mathcal{H}_q + 2\lambda}{4\lambda} = \alpha_3.$$

Finally, for all $\alpha \in \left(\frac{1}{2}, \frac{\rho}{\lambda}\right)$ we have

$$g(-\delta_1) < H_{4h-1} < g(r_h) < H_{4h}, \quad g(r_{2h+1}) > H_{4h+1} \quad \text{and} \quad g(-\delta_2) > H_{4h+2},$$

which finishes the proof. $\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad\qquad$ $\square$

T h e p r o o f o f T h e o r e m 60 f o r $\frac{1}{2} \leq \alpha < \frac{\rho}{\lambda}$. Consider the intersection point of the graph of g with the line $v = H_{4h+1} = \lambda - \rho$. The first coordinate of this point is given by

$$t_1 = \frac{-\mathcal{H}_q}{1 + (\lambda - \rho)\mathcal{H}_q} = \frac{-\rho}{1 + \rho\lambda}.$$

Note that $t_1 \in (l_h, -\delta_2)$. We find $T_\alpha(t_1) = \frac{1}{\rho} - \lambda$ and it easily follows that we have $T_\alpha(t_1) \in (l_{h+1}, r_1)$ for all $\alpha < \frac{\rho}{\lambda}$. From Theorem 58 we conclude that $T_\alpha^h(t_1) = (S^{-1}T)^{h-1}S^{-2}T(t_1)$. From Lemma 42 and relations (12) and (14) we get

$$
\begin{aligned}
(S^{-1}T)^{h-1}S^{-2}T &= \begin{bmatrix} -B_h & -B_{h-1} \\ B_{h-1} & B_{h-2} \end{bmatrix} \begin{bmatrix} -2\lambda & -1 \\ 1 & 0 \end{bmatrix} \\
&= B_{h+1} \begin{bmatrix} -\lambda + 1 & -\lambda^2 + \lambda + 1 \\ \lambda^2 - \lambda - 1 & \lambda^3 - \lambda^2 - 2\lambda + 1 \end{bmatrix} \begin{bmatrix} -2\lambda & -1 \\ 1 & 0 \end{bmatrix} \\
&= B_{h+1} \begin{bmatrix} \lambda^2 - \lambda + 1 & \lambda - 1 \\ -\lambda^3 + \lambda^2 + 1 & -\lambda^2 + \lambda + 1 \end{bmatrix}.
\end{aligned}
$$

We find $T_\alpha^h(t_1) = -\dfrac{\lambda - \rho - 1}{\lambda(\lambda - \rho - 1) + \rho - 1}$, and using $\rho^2 + (2 - \lambda)\rho - 1 = 0$ we find

$$g\left(T_\alpha^h(t_1)\right) = \frac{-1}{\mathcal{H}_q} - \frac{1}{T_\alpha^h(t_1)} = -\rho - \frac{1}{\rho} + \lambda + \frac{\rho - 1}{\lambda - \rho - 1} = \lambda - \frac{1}{\rho} = H_{4h-1}.$$

So $\left(T_\alpha^h(t_1), \lambda - \frac{1}{\rho}\right)$ is the intersection point of the graph of g with the height $v = H_{4h-1}$. From the proof of Lemma 62 it follows that $T_\alpha^h(t_1) \in (-\delta_1, r_h)$. We find that

$$T_\alpha^{h+1}(t_1) = T_\alpha\left(T_\alpha^h(t_1)\right) = -\lambda + \frac{\rho - 1}{\lambda - \rho - 1}.$$

Since $T_\alpha^{h+1}(t_1) < r_{h+1}$, we conclude that

$$T_\alpha^{2h+1}(t_1) = (S^{-1}T)^h S^{-2}T(S^{-1}T)^{h-1}S^{-2}T(t_1)$$

$$= B_{h+1}\begin{bmatrix} -1 & -\lambda+1 \\ \lambda-1 & \lambda^2-\lambda-1 \end{bmatrix}\left(-\lambda + \frac{\rho-1}{\lambda-\rho-1}\right)$$

$$= \frac{\lambda-2\rho}{2+\lambda(\rho-2)} = \frac{-\rho}{1+\lambda\rho} = t_1.$$

We find that $(t_1, \lambda - \rho)$ is a fixed point of $\mathcal{T}_\alpha^{2h+1}$.

The rest of the proof is similar to the even case for $\alpha \in \left(\frac{1}{2}, \frac{1}{\lambda}\right)$. In this case $(\tau_k, \nu_k) = T_\alpha^{-k(2h+1)}(l_h, \lambda - \rho)$. We have $\tau_{k-1} < \tau_k$ and $\lim_{k\to\infty} \tau_k = t_1$. From $c_k = \Theta_n(\tau_k, \nu_k) = \frac{-\tau_{k-1}}{1+\tau_{k-1}\nu_{k-1}}$, we find

$$c_k < c_{k-1} \quad \text{and} \quad \lim_{k\to\infty} c_k = \frac{-1}{\frac{1}{t_1}+\lambda-\rho} = \frac{-1}{\frac{1+(\lambda-\rho)\mathcal{H}_q}{-\mathcal{H}_q}+\lambda-\rho} = \mathcal{H}_q.$$

$\square$

4.2. Odd case for $\alpha = \frac{\rho}{\lambda}$

H. Nakada recently observed that the dynamical systems $(\Omega_{1/2}, \mu_{1/2}, \mathcal{T}_{1/2})$ and $(\Omega_{\rho/\lambda}, \mu_{\rho/\lambda}, \mathcal{T}_{\rho/\lambda})$ are metrically isomorphic via M given in (49). In Section 3.2 we used this isomorphism to derive results for $(\Omega_{1/\lambda}, \mu_{1/\lambda}, \mathcal{T}_{1/\lambda})$ from $(\Omega_{1/2}, \mu_{1/2}, \mathcal{T}_{1/2})$ by applying Theorem 51. For odd q and $\alpha = \frac{\rho}{\lambda}$ we can do the same and for this case the proof of Theorem 60 is similar to the one for the even case with $\alpha = \frac{1}{\lambda}$ given in Section 3.2.

For $q = 3$ this result (where one can take $K = 1$) had been known for a long time for the nearest integer continued fraction expansion (the case $\alpha = 1/2$) and for the singular continued fraction expansion ($\alpha = \frac{1}{2}(\sqrt{5}-1)$), c.f. [9].

4.3. Odd case for $\alpha \in (\frac{\rho}{\lambda}, 1/\lambda]$

In this last case the natural extension Ω_α is given by $\Omega_\alpha = \bigcup_{n=1}^{4h+3} J_n \times [0, H_n]$. With intervals given by

$$J_{2n-1} = [l_{n-1}, r_n) \quad \text{for} \quad n = 1, 2, \ldots, h+1$$

$$J_{2n} = [r_n, l_n) \quad \text{for} \quad n = 1, 2, \ldots, h \quad \text{and} \quad J_{2h+2} = [r_{h+1}, r_0),$$

and heights defined by

$$H_1 = \frac{1}{\lambda+1}, H_2 = \frac{1}{\lambda} \quad \text{and} \quad H_n = \frac{1}{\lambda-H_{n-2}} \quad \text{for } n = 3, 4, \ldots, 2h+2.$$

In [5] was shown that $H_{2h} = \lambda - 1$, $H_{2h+1} = \frac{\lambda}{2}$ and $H_{2h+2} = 1$. If $\alpha = \frac{1}{\lambda}$ the intervals J_{2n-1} are empty; see Theorem 58. Again we have $l_h = \frac{\alpha\lambda-1}{1-\alpha\lambda(\lambda-1)}$.

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4.3.1. Points in $\mathcal{D}^+$

We saw in Section 4 that $\mathcal{D}^+ \neq \emptyset$. The leftmost point of $\overline{\mathcal{D}^+}$ is given by (ρ, ρ). Using the same techniques as in the rest of this article yields

$$T_\alpha^{h+1}(\rho) = \left(S^{-1}T\right)^h ST(\rho)$$

$$= B_{h+1} \begin{bmatrix} -1 & -1 \\ 1 & \lambda - 1 \end{bmatrix} (-\rho) = \frac{\rho - 1}{-\rho + \lambda - 1} = \rho.$$

It easily follows that $\mathcal{T}_\alpha^{h+1}(\rho, \rho) = (\rho, \rho)$.

REMARK 63. In [3] it was shown that $\rho = \overline{[+1 : 1, (-1 : 1)^h]}$ from which immediately follows $T_\alpha^{h+1}(\rho) = \rho$.

We note that $\mathcal{T}_\alpha$ 'flips' $\mathcal{D}^+$ in the first step, in the sense that $\mathcal{T}_\alpha(\rho, \rho)$ is the rightmost point of $\mathcal{T}(\overline{D^+})$. The orientation is preserved in the next h steps, so we know that the rightmost point of $\mathcal{T}_\alpha^{h+1}(\overline{\mathcal{D}^+})$ is given by $\mathcal{T}_\alpha^{h+1}(\rho, \rho) = (\rho, \rho)$. Therefore we find that

$$\mathcal{T}_\alpha^{h+1}\left(\mathcal{D}^+\right) \cap \mathcal{D}^+ = \emptyset.$$

So after one round all points in $\mathcal{D}^+$ are flushed out of $\mathcal{D}$. Furthermore, it is straightforward to check that

$$\mathcal{T}_\alpha\left(\mathcal{D}^+\right) \subset \mathcal{D}, \quad \text{and that} \quad \mathcal{T}_\alpha^i\left(\mathcal{D}^+\right) \cap \mathcal{T}_\alpha^j\left(\mathcal{D}^+\right) = \emptyset \quad \text{for} \quad 0 \leq i < j \leq h+1.$$

4.3.2. Points in $\mathcal{D}^-$

As in the previous section we only describe the part of $\mathcal{D}^-$ on the right hand side of the line $t = -\delta_1$.

LEMMA 64. If $\alpha \in \left(\frac{\rho}{\lambda}, \alpha_4\right]$, then $\mathcal{D}^-$ consists of two components: $\mathcal{D}_1$ bounded by the line $t = -\delta_1$ from the left, the line $v = H_{2h} = \lambda - 1$ from above and the graph of g from below and $\mathcal{D}_2$ bounded by the line $t = l_h$ from the left, the line $v = H_{2h+1} = \frac{\lambda}{2}$ from above and the graph of g from below.

If $\alpha \in \left(\alpha_4, \frac{1}{\lambda}\right]$, then $\mathcal{D}^- = \mathcal{D}_1$.

P r o o f. For all $\alpha \in \left(\frac{\rho}{\lambda}, \frac{1}{\lambda}\right]$ we have that $g(-\delta_1) < H_{2h} < g(l_h)$. Furthermore, $g(l_h) < H_{2h+1}$ if and only if $\alpha < \alpha_4$. $\square$

Again we must distinguish between two subcases; also see Figure 9.

P r o o f o f T h e o r e m 60 f o r $\frac{\rho}{\lambda} < \alpha \leq \alpha_4$. First we note that $T^{h+1}(-\delta_1) = l_h$ and thus after one round all points in $\mathcal{D}_1$ are either flushed or send to $\mathcal{D}_2$.
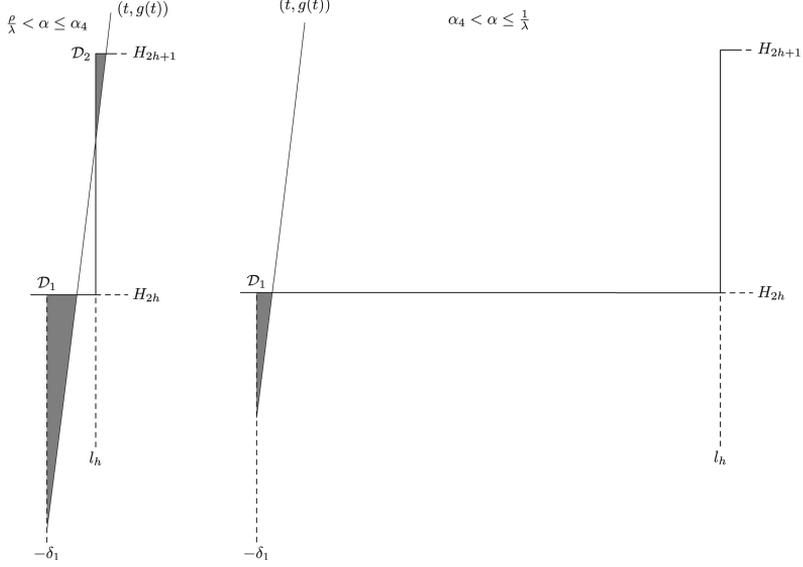
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FIGURE 9. On the left we used $\alpha = 0.50098 < \alpha_4$, on the right we use $\alpha = 0.52 > \alpha_4$.

We look at the orbit of l_h under T_α. We find $T_\alpha(l_h) = \frac{1+\alpha\lambda(\lambda+1)-2\lambda}{1-\alpha\lambda}$ and some calculations show that $r_1 < T_\alpha(l_h) < l_1$. We conclude that

$$T_\alpha^h(l_h) = (S^{-1}T)^{h-1}S^{-2}T(l_h) = \left[\begin{array}{cc} \lambda^2 - \lambda + 1 & \lambda - 1 \\ -\lambda^3 + \lambda^2 + 1 & -\lambda^2 + \lambda + 1 \end{array} \right] (l_h)$$

$$= \frac{2\lambda + (\alpha - 1)\lambda^2 - 2}{((1-\alpha)\lambda^2 + 2\alpha + 1 - 2\lambda)\lambda}.$$

One can check that for $\alpha > \frac{\rho}{\lambda}$ we have $-\delta_1 < T_\alpha^h(l_h) < l_h$. We find

$$T_\alpha^{h+1}(l_h) = T_\alpha\left(T_\alpha^h(l_h)\right) = \frac{\left(\lambda^2 - 2\lambda - \alpha(\lambda^2 + 2) + 3\right)\lambda}{2\lambda + (\alpha - 1)\lambda^2 - 2} < r_1.$$

So we finally conclude that the image of l_h after one round of $2h + 1$ steps is given by

$$T_\alpha^{2h+1}(l_h) = (S^{-1}T)^h S^{-2}T(S^{-1}T)^{h-1}S^{-2}T(l_h) = \left[\begin{array}{cc} \lambda^2 + 2 & \lambda \\ -2\lambda^2 + \lambda & 2 - 2\lambda \end{array} \right] (l_h)$$

$$= \frac{(-\alpha + 1)\lambda^2 - 2\alpha\lambda - \lambda + 2}{(3\alpha - 2)\lambda^2 + (3 - 2\alpha)\lambda - 2}.$$

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The right end point of $\mathcal{D}_2$ is given by $\left(\frac{-2\mathcal{H}_q}{\lambda\mathcal{H}_q+2}, \frac{\lambda}{2}\right)$. Since for $\frac{\rho}{\lambda} < \alpha \leq \alpha_4$ we have

$$\frac{-2\mathcal{H}_q}{\lambda\mathcal{H}_q + 2} < \frac{(-\alpha+1)\lambda^2 - 2\alpha\lambda - \lambda + 2}{(3\alpha-2)\lambda^2 + (3-2\alpha)\lambda - 2} < 0,$$

we find that all points are flushed out of $\mathcal{D}_2$ after one round. So all points in $\mathcal{D}_1$ are flushed after at most $3h + 2$ steps. $\qquad\square$

P r o o f o f T h e o r e m 60 f o r $\alpha_4 < \alpha \leq \frac{1}{\lambda}$. All points are flushed out of $\mathcal{D}_1$ after $h + 1$ steps since the line $t = -\delta_1$ is mapped by T_α to the line $t = l_0$. So after $h + 1$ steps all points in $\mathcal{D}$ are mapped to points that lie on the right hand side of the line $t = l_h$ and thus outside of $\mathcal{D}_1$.

We need to check that $\mathcal{T}_\alpha^{h+1}(\mathcal{D}_1) \cap \mathcal{D}^+ = \emptyset$. The rightmost vertex of $\overline{\mathcal{D}_1}$ is given by $\left(\frac{-1}{\lambda-1+\frac{1}{\mathcal{H}_q}}, \lambda-1\right)$. With similar techniques as before we find that applying $(h + 1)$-times $\mathcal{T}_\alpha$ to the rightmost vertex of $\mathcal{D}_1$ yields as first coordinate

$$T_\alpha^{h+1}\left(\frac{-1}{\lambda-1+\frac{1}{\mathcal{H}_q}}\right)$$

$$= \begin{bmatrix} -\lambda & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \lambda^2-\lambda+1 & \lambda-1 \\ -\lambda^3+\lambda^2+1 & -\lambda^2+\lambda+1 \end{bmatrix} \left(\frac{-1}{\lambda-1+\frac{1}{\mathcal{H}_q}}\right)$$

$$= \frac{1-2\mathcal{H}_q}{1+(\mathcal{H}_q-1)\lambda} < \rho.$$

This completes the proof. $\qquad\square$

5. Borel and Hurwitz constants for α-Rosen fractions

In this section we first prove the Borel-type Theorem 10 and then derive a Hurwitz-type result for certain values of α.

5.1. Borel for α-Rosen fractions

Let $q \geq 3$ be an integer. Recall from Remark 15 that for all $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$ and every G_q-irrational $x \in [(\alpha-1)\lambda, \alpha\lambda)$ the future t_n and past v_n satisfy

$$\mathcal{T}_\alpha^n(x, 0) = (t_n, v_n) \quad \text{for all} \quad n \geq 0. \tag{65}$$

We denote by r the number of steps in a round, so $r = p - 1$ for even q and $r = 2h + 1$ for odd q. Furthermore, for even q we define $\rho = 1$. Compare the following with Lemma 12 of [13].

Lemma 66. *Let either q be even and $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$ or q be odd and $\alpha \in \left[\frac{1}{2}, \frac{\rho}{\lambda}\right]$. Let $\mathcal{F}$ denote the fixed point set in $\mathcal{D}$ of $\mathcal{T}_\alpha^r$. Then*

(i) $\mathcal{F} = \left\{ \mathcal{T}_\alpha^i \left(\frac{-\rho}{1+\lambda\rho}, \lambda - \rho \right) \,\middle|\, i = 0, 1, \ldots, r-1 \right\}$;

(ii) *For every x and every $n \geq 0$, $(t_n, v_n) \notin \mathcal{F}$;*

(iii) *For every G_q-irrational number x there are infinitely many n for which $(t_n, v_n) \notin \mathcal{D}$;*

(iv) *For each $i = 0, 1, \ldots, r-1$, let $x_i = \mathcal{T}_\alpha^i \left(\frac{-\rho}{1+\lambda\rho} \right)$. Then for all $n \geq 0$, $\mathcal{T}_\alpha^n(x_i, 0) \notin \mathcal{D}$. However, $\mathcal{T}_\alpha^{kr}(x_i, 0)$ converges from below on the vertical line $x = x_i$ to $\mathcal{T}_\alpha^{\,i} \left(\frac{-\rho}{1+\lambda\rho}, \lambda - \rho \right)$.*

P r o o f. Assume that q is even and $\alpha \in (\frac{1}{2}, \frac{1}{\lambda})$, the other cases can be proven in a similar way. In this case $r = p-1$ and we have by Corollary 44 that $(\frac{-1}{\lambda+1}, \lambda-1)$ is a fixed point of $\mathcal{T}_\alpha^{p-1}$. It follows that points in the $\mathcal{T}_\alpha$-orbit of $(\frac{-1}{\lambda+1}, \lambda - 1)$ must also be fixed points of $\mathcal{T}_\alpha^{p-1}$, which proves (i). In each fixed point of $\mathcal{T}_\alpha^{p-1}$ both of the coordinates have a periodic infinite expansion. For (ii) we note that by definition v_n has a finite expansion of length n and therefore for every x and every n we have $v_n \notin \mathcal{F}$. We conclude from the section on flushing on page 34, that for every G_q-irrational number x there are infinitely many n for which $(t_n, v_n) \notin \mathcal{D}$, which is (iii). Finally, for each $i = 0, 1, \ldots, r-1$ and every $n \geq 0$ the points $\mathcal{T}_\alpha^n(x_i, 0)$ are below the graph of f. The fixed points $\mathcal{T}_\alpha^{\,i}(\frac{-1}{1+\lambda}, \lambda - 1)$ are attractors for these points, cf. the proof of Lemma 47. $\square$

P r o o f o f T h e o r e m 10. Let $q \geq 3$ be an integer and let x be a G_q-irrational. We first assume that we do not have a finite spectrum, so if q is even, we consider all $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$ and if q is odd we assume $\alpha \in \left[\frac{1}{2}, \frac{\rho}{\lambda}\right]$.

From Lemma 66 (ii) we see that (t_n, v_n) can never be a fixed point for any $n \geq 0$. From (iii) we know that here are infinitely many n for which $(t_n, v_n) \notin \mathcal{D}$, so there are infinitely many $n \in \mathbb{N}$ for which

$$q_n^2 \left| x - \frac{p_n}{q_n} \right| \leq \mathcal{H}_q.$$

It remains to show that also in this case $\mathcal{H}_q$ cannot be replaced by a smaller constant. Take x such that $t_1 = \frac{-\rho}{1+\lambda\rho}$. By definition of Ω_α we know that $v_1 \leq \lambda - 1$ and since v_1 has a finite expansion we find $v_1 < \lambda - 1$. For all $l \geq 1$ we have $(t_{1+rl}, v_{1+rl}) \notin \mathcal{D}$ and for every $0 \leq i < r$ one has

$$\lim_{l \to \infty} \mathcal{T}_\alpha^i(t_{1+rl}, v_{1+rl}) = \mathcal{T}_\alpha^i \left(\frac{-\rho}{1+\lambda\rho}, \lambda - \rho \right).$$

So, $\mathcal{H}_q$ cannot be replaced by a smaller constant.

Finally, assume q is odd and $\alpha \in \left(\frac{\rho}{\lambda}, \frac{1}{\lambda}\right]$. From the finite spectrum in Theorem 60 it immediately follows that in this case there are infinitely many n for which

$$q_n^2 \left| x - \frac{p_n}{q_n} \right| \leq \mathcal{H}_q.$$

It remains to show that in this case the constant $\mathcal{H}_q$ cannot be replaced by a smaller constant. Consider (ρ, ρ), the fixed point of $\mathcal{T}_\alpha^{h+1}$. We find

$$\mathcal{T}_\alpha(\rho, \rho) = \left(\frac{1}{\rho} - \lambda, \frac{1}{\lambda + \rho} \right).$$

Note that $H_1 = \frac{1}{\lambda+1} < \frac{1}{\lambda+\rho} < \frac{1}{\lambda} = H_2$. Furthermore,

$$f\left(\frac{1}{\rho} - \lambda\right) = \frac{\mathcal{H}_q}{1 - \mathcal{H}_q\left(\frac{1}{\rho} - \lambda\right)} = \frac{\rho}{\rho^2 + 1 - \rho\left(\frac{1}{\rho} - \lambda\right)} = \frac{1}{\lambda + \rho}.$$

So $\mathcal{T}_\alpha(\rho, \rho)$ lies on the graph of f bounding $\mathcal{D}$. Points in $\mathcal{D}$ on the left hand side of $x = -\delta_1$ are mapped into $\mathcal{D}$ by $\mathcal{T}_\alpha$ and we find $\mathcal{T}_\alpha^2(\rho, \rho), \mathcal{T}_\alpha^3(\rho, \rho), \ldots, \mathcal{T}_\alpha^{h-1}(\rho, \rho)$ all are in $\mathcal{D}$.

It is easy to check that $\mathcal{T}_\alpha(\frac{-1}{\lambda+\rho}, \lambda - \frac{1}{\rho}) = (\rho, \rho)$ and that $g(\frac{-1}{\lambda+\rho}) = \lambda - \frac{1}{\rho}$. We conclude that $\mathcal{T}_\alpha^h(\rho, \rho) = \mathcal{T}_\alpha^{-1}(\rho, \rho) = (\frac{-1}{\lambda+\rho}, \lambda - \frac{1}{\rho})$ lies on the graph of g.

Now consider any point $(t_n, v_n) = (\rho, y)$, since ρ has a periodic infinite expansion we know $y \neq \rho$. However the periodic orbit of (ρ, ρ) is an attractor of the orbit of (ρ, y), so $\lim\limits_{k \to \infty} \mathcal{T}_\alpha^{k(h+1)}(\rho, y) = (\rho, \rho)$. It follows that the constant $\mathcal{H}_q$ is best possible in this case. □

5.2. Hurwitz for α-Rosen fractions

For odd q and some values of α we can generalize Theorem 10 to a Hurwitz-type theorem, which is the Haas-Series result mentioned in Section 1.1. From [2] it follows that for all $\alpha \in \left[\frac{1}{2}, \frac{1}{\lambda}\right]$, for all $z \geq 0$ and for almost all x, the limit

$$\lim_{n \to \infty} \frac{1}{n} \#\{1 \leq j \leq n | \Theta_j(x) \leq z\}$$

exists and equals the distribution function F_α, which satisfies

$$F_\alpha(z) = \bar{\mu}\left(\left\{(t, v) \in \Omega_\alpha \left| v \leq f(t) = \frac{z}{1 - zt}\right.\right\}\right),$$

where $\bar{\mu}$ is the invariant measure for $\mathcal{T}_\alpha$ given in [5]. Defining the Lenstra constant $\mathcal{L}_\alpha$ by

$$\mathcal{L}_a = \max\left\{c > 0 \left| \left(t, \frac{c}{1 - ct}\right) \in \Omega_\alpha \right., \text{ for all } t \in [l_0, r_0]\right\}. \tag{67}$$

As mentioned in Section 1.2, the distribution function F_α is a linear map with positive slope for $z \in [0, \mathcal{L}_\alpha]$. Nakada showed in [17] that the Lenstra constant is equal to the Legendre constant whenever the latter constant exists. In his article he particularly mentioned Rosen fractions and α-expansions, but this result also holds for α-Rosen fractions. So if p/q is a G_q-rational and

$$q^2 \left| x - \frac{p}{q} \right| < \mathcal{L}_\alpha ,$$

then p/q is an α-Rosen convergent of x.

Since for the standard Rosen fractions (where $\alpha = \frac{1}{2}$) one has that $\mathcal{L}_\alpha < \mathcal{H}_q$, the Haas-Series result does not follow from Theorem 10; see also the discussion on the results of Legendre, Borel and Hurwitz in Section 1.2.

One wonders whether α-Rosen fractions could yield a continued fraction proof of the Haas-Series result for particular values of α. Proposition 4.3 of [5] states that for even α-Rosen-fractions

$$\mathcal{L}_a = \min \left\{ \frac{\lambda}{\lambda + 2}, \frac{\lambda(2 - \alpha\lambda^2)}{4 - \lambda^2} \right\} .$$

Since $\mathcal{L}_\alpha < \mathcal{H}_q = \frac{1}{2}$, we see that a direct continued fraction proof of a Hurwitz-result cannot be given in this case. In [5] the more involved formula for $\mathcal{L}_\alpha$ for odd α-Rosen fractions was not given. For odd q we have the following proposition.

PROPOSITION 68. *Let $q \geq 3$ be an odd integer and let $\alpha_L = \frac{\mathcal{H}_q}{\lambda(1 - \mathcal{H}_q)}$. Then $\mathcal{L}_\alpha < \mathcal{H}_q$ for $\alpha \in [1/2, \alpha_L)$, while $\mathcal{L}_\alpha = \frac{\alpha\lambda}{\alpha\lambda + 1} > \mathcal{H}_q$ for $\alpha \in [\alpha_L, 1/\lambda]$.*

P r o o f. For every $\alpha \in [1/2, \alpha_L)$ there is a $C < \mathcal{H}_q$ such that $(t, \frac{C}{1 - Ct}) \notin \Omega_\alpha$. We only prove this for $\alpha = \rho/\lambda$. Consider the point $(\rho, \frac{C}{1 - C\rho})$. This point is in Ω_ρ if the y-coordinate is smaller than top height $\frac{\lambda}{2}$. We have

$$\frac{C}{1 - C\rho} < \frac{\lambda}{2} \quad \text{if and only if} \quad C < \frac{\lambda}{\lambda\rho + 2}.$$

So by (67) we have that

$$\mathcal{L}_\alpha = \frac{\lambda}{\lambda\rho + 2} < \mathcal{H}_q.$$

Let $\alpha \in [\alpha_L, 1/\lambda]$. Consider the point $(r_1, \frac{C}{1 - Cr_1})$, this point is in Ω_α if the y-coordinate is smaller than $H_1 = \frac{1}{\lambda + 1}$. Using $r_1 = \frac{1}{\alpha\lambda} - \lambda$ we find that $\frac{C}{1 - Cr_1} \leq \frac{1}{\lambda + 1}$ if and only if $C \leq \frac{\alpha\lambda}{\alpha\lambda + 1}$. For $C = \frac{\alpha\lambda}{\alpha\lambda + 1}$ we easily find that all points $(t, \frac{C}{1 - Ct})$ with $t \in (l_0, r_0)$ are in Ω_α, so $\mathcal{L}_\alpha = \frac{\alpha\lambda}{\alpha\lambda + 1}$. Finally, we see that

$$\mathcal{L}_\alpha > \mathcal{H}_q \quad \text{if and only if} \quad \alpha > \alpha_L. \qquad \square$$

Thus the Hurwitz-type theorem of Haas-Series in the case of odd index q follows from Theorem 10, Proposition 68 and Nakada's result from[17] by using any $\alpha \in [\alpha_L, 1/\lambda]$.

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